

# Special Mathematics Lecture

## Statistics

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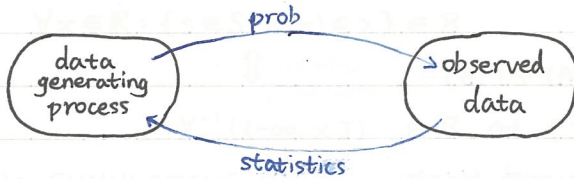
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Handwritten notes taken by L. Zhang

# Statistics

Course is based on [CB] Statistical inference.

## Probability and Statistics



## I Probability

### I.1 Probability space

#### Ingredients

- 1)  $S = \Omega$  is a set called the SAMPLE SPACE set of all outcomes of an experiment
- 2) Any subset  $A \subset S$  is called an EVENT

3) An EVENT SPACE  $\mathcal{B} = \mathcal{F}$  is a collection of events satisfying:

1)  $\emptyset$  and  $S \in \mathcal{B}$   $\emptyset$  is the empty set

2) If  $A \in \mathcal{B}$  then  $A^c = S \setminus A$  S minus A or the complement of A in S  $\in \mathcal{B}$

3) If  $A_j \in \mathcal{B}$  for  $j=1, 2, 3, \dots$  infinite but countable family then  $\bigcup_{j=1}^{\infty} A_j \in \mathcal{B}$

}  $\sigma$ -ALGEBRA

Recall:  $(A \cup B)^c = A^c \cap B^c$   
 $(A \cap B)^c = A^c \cup B^c$  } De Morgan's Law

#### Examples

1) If  $S = \{a_1, a_2, \dots, a_n\}$  then  $\mathcal{B} = \{\text{all subset of } S\}$  power set of S

2) If  $S = \mathbb{R}$ , then we choose  $\mathcal{B}$  as the family of subsets generated by intervals  $(a, b) \forall a < b$ .  
 $\mathcal{B}$  is called the BOREL ALGEBRA of  $\mathbb{R}$  denoted by  $\sigma_{\mathbb{R}}$ .

(We can do the same for  $[a, b]$ )

$\Rightarrow \exists$  some subsets of S to which we cannot give a weight

4) a PROBABILITY FUNCTION  $P = \mathbb{P}$  is a map  $P: \mathcal{B} \rightarrow \mathbb{R}$  such that (s.t.)

1)  $P(A) \geq 0 \quad \forall A \in \mathcal{B}$

2)  $P(S) = 1$  and  $P(\emptyset) = 0$

3) If  $A_j \cap A_k = \emptyset \quad \forall j, k$  then  $P\left(\bigcup_{j=1}^{\infty} A_j\right) = \sum_{j=1}^{\infty} P(A_j)$

} axioms of probability  
OR  
Holmogorov's axioms

## Propositions

$$1) P(A) \leq 1 \text{ and } P(A^c) = 1 - P(A) \quad \forall A \in \mathcal{B}$$

$$2) P(A \cup B) = P(A) + P(B) - P(A \cap B) \Leftrightarrow$$

$$P(A \cap B) = P(A) + P(B) - P(A \cup B) \geq P(A) + P(B) - 1 \quad \text{Bonfrevioni's inequality}$$

$$3) \text{ If } B \subset A \text{ then } P(B) \leq P(A)$$

$$4) \text{ If } C_j \in \mathcal{B} \text{ s.t. } \bigcup_{j=1}^{\infty} C_j = S \text{ and } C_j \cap C_k = \emptyset \quad \forall j, k \quad \text{partition of } S$$

$$\text{then } P(A) = \sum_{j=1}^{\infty} P(A \cap C_j) \quad \forall A \in \mathcal{B}$$

Def.  $(S \text{ sample space, } \mathcal{B} \text{ event space, } P \text{ probability function})$  is called a PROBABILITY SPACE.

Exercise: Find the number of arrangement of  $n$  objects from  $S$ . p.14~15 [CB]

	without replacement	with replacement
ordered		
unordered		

## Ex. 1.2.20

Def. If  $A, B \in \mathcal{B}$  and if  $P(B) > 0$

we define the CONDITIONAL PROBABILITY of  $A$  given  $B$  by

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Observe that  $P(A \cap B) = P(A|B)P(B)$

$$\text{||}$$

$$P(B \cap A) = P(B|A)P(A)$$

$$\Rightarrow P(A|B) = P(B|A) \frac{P(A)}{P(B)}$$

## Example of 2 dice

$A = \{\text{black dice is 1}\}$ ;  $B = \{\text{red dice is 1}\}$

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{1/36}{1/6} = \frac{1}{6}$$

More generally: (Bayes Rule) Exercise: check for its application

If  $\{C_j\}_{j=1}^{\infty}$  is a partition of  $S$

$$P(C_j|B) = \frac{P(B|C_j)P(C_j)}{\sum_k P(B|C_k)P(C_k)} \quad \text{if } P(B) \neq 0$$

$$\left. \begin{array}{c} \text{||} \\ P(B \cap C_k) \end{array} \right\} = P(B)$$

Def. Let  $A, B \in \mathcal{B}$ , they are INDEPENDENT if  $P(A \cap B) = P(A)P(B)$

Def. A collection of events  $A_1, A_2, \dots \in \mathcal{B}$  are MUTUALLY INDEPENDENT if

$$\forall A_{i_1}, A_{i_2}, \dots, A_{i_n} : P\left(\bigcap_{j=1}^n A_{i_j}\right) = \prod_{j=1}^n P(A_{i_j})$$

## I.2 Random variable

Def. a RANDOM VARIABLE  $X$  on a probability space  $(S, \mathcal{B}, P)$

is a function  $X: S \rightarrow \mathbb{R}$  satisfying

$$\forall x \in \mathbb{R}: \{s \in S \mid X(s) \leq x\} \in \mathcal{B}$$



$$X^{-1}((-\infty, x]) \in \mathcal{B} \Leftrightarrow \{X \leq x\} \in \mathcal{B}$$

Def. The CUMULATIVE DISTRIBUTION FUNCTION (CDF) associated to  $X$

is the function  $F_X: \mathbb{R} \rightarrow [0, 1]$  defined for any  $x \in \mathbb{R}$  by

$$F_X(x) := P(\{X \leq x\})$$

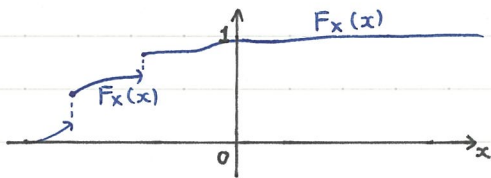
Properties

1)  $F_X(x) \leq F_X(y)$  if  $x \leq y$  (increasing / monotonic non-decreasing)

2)  $\lim_{x \rightarrow -\infty} F_X(x) = 0$ ;  $\lim_{x \rightarrow \infty} F_X(x) = 1$

3)  $\lim_{\varepsilon \rightarrow 0} F_X(x + \varepsilon) = F_X(x)$  (right continuous)

One has



Thm. Whenever  $F: \mathbb{R} \rightarrow [0, 1]$  satisfies properties 1) ~ 3),

there exists  $(S, \mathcal{B}, P)$  and a random variable  $X$  such that

$$F_X = F.$$

⚠ non-unique

Exercise: Summary ~~the~~ one distribution in the handout for this lecture, writing the properties and an example for this distribution.

(do in pairs)

Remark: From  $F_X$  one gets

$$\bullet P(a < X \leq b) = P(\{\omega \in \Omega \mid X(\omega) \in (a, b]\}) = F_X(b) - F_X(a)$$

$$\bullet \text{Since } P(X < a) = \lim_{\varepsilon \searrow 0} F_X(a - \varepsilon)$$

$$\Rightarrow P(a \leq X \leq b) = F_X(b) - \lim_{\varepsilon \searrow 0} F_X(a - \varepsilon)$$

$$\Rightarrow P(X = a) = F_X(a) - \lim_{\varepsilon \searrow 0} F_X(a - \varepsilon) \quad \text{see the figure in p. 3}$$

↑ non-zero whenever  $F_X$  has a jump at  $a$

Def.

1)  $X$  is CONTINUOUS if " $F_X$  has no jump", or

$$\lim_{\varepsilon \searrow 0} F_X(a - \varepsilon) = F_X(a) \quad \forall a \in \mathbb{R}$$

2)  $X$  is (ABSOLUTELY) CONTINUOUS if

$$\exists f_X: \mathbb{R} \rightarrow \mathbb{R} \text{ such that } F_X(x) = \int_{-\infty}^x f_X(y) dy; \quad f_X \in L^1(\mathbb{R})$$

↑ PROBABILITY DENSITY FUNCTION (PDF)

3)  $X$  is DISCRETE if  $X(\Omega) \subset \mathbb{R}$  is finite or countable.

↕ (in bijection with  $\mathbb{N}$ )

4)  $X$  can be SINGULAR CONTINUOUS,

or a mixture of abs. continuous, sing. continuous and discrete.

Remark

When  $X$  is discrete, the function

$$f_X: \mathbb{R} \rightarrow \mathbb{R}, \quad f_X(x) := F_X(x) - \lim_{\varepsilon \searrow 0} F_X(x - \varepsilon) \text{ is called the}$$

PROBABILITY MASS FUNCTION (pmf).

$$\text{Observe that } \sum_{x \in \mathbb{R}} f_X(x) = 1.$$

$$\text{And for the pdf } \int_{-\infty}^{\infty} f_X(y) dy = 1.$$

Use of pdf and pmf:

If  $I \subset \mathbb{R}$  (Borel subset of  $\mathbb{R}$ ), then

$$P(x \in I) = P(\{x \in \Omega \mid X(x) \in I\}) = \begin{cases} \int_I f_X(y) dy & \text{in continuous case} \\ \sum_{x \in I} f_X(x) & \text{in discrete case} \end{cases}$$

Remark:

The set  $\{X(s) | s \in S\}$  is called the **IMAGE** of the random variable  $X$ .

We denote it by  $\text{Im}(X)$  or  $\text{Ran}(X)$ .

Remark:

If a pdf or a pmf depends on some parameters  $\theta_1, \theta_2, \dots, \theta_n$ , then we write

$$f(\cdot | \theta_1, \dots, \theta_n) : \mathbb{R} \mapsto \mathbb{R}$$

Remark:

The range of a discrete r.v. is countable, while the range of a continuous one is not countable.

### I.3 Transformations and expectations

We always use  $(S, \mathcal{B}, P)$  for a prob. space and  $X$  for a random variable.

Let  $g : \mathbb{R} \mapsto \mathbb{R}$  and consider  $g(X) := g \circ X$

$$\begin{array}{c} S \xrightarrow{X} \mathbb{R} \xrightarrow{g} \mathbb{R} \\ \underbrace{\hspace{10em}}_{g \circ X} \end{array}$$

Lemma:  $g(X)$  is a random variable if  $g : \mathbb{R} \mapsto \mathbb{R}$  is **BOREL MEASURABLE**.

It means that  $\forall A \in \sigma_B : g^{-1}(A) \in \sigma_B$

$\leftarrow$  Borel algebra on  $\mathbb{R}$

Remark: This is a condition satisfied by almost all functions

(for example continuous, or piecewise continuous functions).

Def. If  $X$  is discrete or (absolutely) continuous with pmf or pdf  $f$ ,

then the **EXPECTED VALUE** or **MEAN** of  $X$  is given by

$$E(X) := \int_{-\infty}^{\infty} x f_X(x) dx \text{ or } \sum_x x f(x)$$

if it converges absolutely

$\leftarrow$  Exercise: find an example when

$$(\Leftrightarrow \int_{-\infty}^{\infty} |x| f_X(x) dx < \infty \text{ or } \sum_x |x| f(x) < \infty)$$

$E(X)$  does not exist.

Thm. If  $X$  is continuous or discrete and  $g$  Borel measurable, then

$$E(g(X)) = \int_{\mathbb{R}} g(x) f_X(x) dx$$

whenever it converges absolutely.

Def.  $\text{Var}(X) = E((X - E(X))^2)$

is the **VARIANCE** whenever it exists.

$\sqrt{\text{Var}(X)}$  is called the **STANDARD DERIVATION**.

Remark: If  $E(X) = \mu$  and  $\text{Var}(X) = \sigma^2$ , then by setting

$$Z := \frac{X - \mu}{\sigma} \quad (\text{the STANDARD FORM})$$

one has  $E(Z) = 0$  and  $\text{Var}(Z) = 1$ .

Def. The  $k^{\text{th}}$ -moment of  $X$  are defined by  $E(X^k)$ , and

the central  $k^{\text{th}}$ -moment of  $X$  by  $E((X - E(X))^k)$  whenever they exist.

Also  $M_X(t) := E(e^{tX})$  for  $t \in \mathbb{R}$  is called the moment generating function (mgf).

#### I.4 Multiple random variables

We are going to consider  $n$  random variables  $X_1, X_2, \dots, X_N: S \mapsto \mathbb{R}$

$$\Leftrightarrow \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} =: \underline{x} : S \mapsto \mathbb{R}^N$$

Def. The joint cumulative distribution function associated with  $\underline{X}$  is a function

$$F_{\underline{X}}: \mathbb{R}^N \mapsto [0, 1] \text{ defined for } \underline{x} = (x_1, \dots, x_n) \text{ by}$$

$$F_{\underline{X}}(\underline{x}) := F_{X_1, \dots, X_N}(x_1, \dots, x_n)$$

$$:= P(\{s \in S \mid X_1(s) \leq x_1, X_2(s) \leq x_2, \dots, X_N(s) \leq x_n\})$$

$$= P(X_j \leq x_j \quad \forall j \in \{1, \dots, N\})$$

If  $\underline{X}$  takes only a countable number of values in  $\mathbb{R}^N$ ,

the joint probability mass function is defined by

$$f_{\underline{X}}(x_1, \dots, x_N) = P(X_1 = x_1, \dots, X_N = x_N)$$

$\underline{X}$  is an absolutely continuous random vector if

$$F_{\underline{X}}(x_1, \dots, x_N) = \int_{-\infty}^{x_1} \int_{-\infty}^{x_2} \dots \int_{-\infty}^{x_N} f_{\underline{X}}(y_1, y_2, \dots, y_N) dy_1 dy_2 \dots dy_N$$

joint probability density function

If  $A \subset \mathbb{R}^N$  (Borel subset) then

$$P(X \in A) = \iint_A \dots \int f_{\underline{X}}(x_1, \dots, x_n) dx_1 \dots dx_n$$

Def.  $X_1, \dots, X_N$  are independent r.v. if

$$P(X_1 \leq x_1, X_2 \leq x_2, \dots, X_N \leq x_n) = P(X_1 \leq x_1) P(X_2 \leq x_2) \dots P(X_N \leq x_n)$$



$$F_{\underline{X}}(x_1, \dots, x_n) = \prod_{j=1}^N F_{X_j}(x_j)$$



$$f_{\underline{X}}(x_1, \dots, x_n) = \prod_{j=1}^N f_{X_j}(x_j)$$

← only in the case of discrete or abs. continuous



Remark: From  $F_{\underline{X}}$  we can obtain  $F_{X_1}$  by the formula

$$F_{X_1}(x_1) = \lim_{y \rightarrow \infty} P(X_1 \leq x_1, X_2 \leq y, X_3 \leq y, \dots, X_N \leq y)$$

↑ marginal cdf

And similarly in the continuous case

$$f_{X_1}(x_1) = \int_{\mathbb{R}} \dots \int_{\mathbb{R}} f_{\underline{X}}(x_1, x_2, \dots, x_n) dx_2 \dots dx_n$$

↑ marginal pdf  
N-1 integrals

As before  $g: \mathbb{R}^N \rightarrow \mathbb{R}$  continuous

$$E(g(\underline{X})) = \iiint_{\mathbb{R}^N} g(\underline{x}) f_{\underline{X}}(\underline{x}) d\underline{x}$$

↑  $dx_1, dx_2, \dots, dx_n$   
N-k random v.

Def. **Conditional pdf or pmf** for  $X_{k+1}, \dots, X_N$  knowing  $X_1, \dots, X_k$  is given by

$$f(x_{k+1}, \dots, x_N | x_1, \dots, x_k) = \frac{f_{\underline{X}}(x_1, \dots, x_N)}{f_{X_1, \dots, X_k}(x_1, \dots, x_k)}$$

if the denominator is not 0.

(Example 4.2.2 + 4.2.4 for motivation)

## I.5 Covariance and correlation

Consider  $X$  and  $Y$  random variables on  $S$ ,

with  $E(X) =: \mu_X$ ,  $E(Y) =: \mu_Y$ ,  $\text{Var}(X) =: \sigma_X^2$ ,  $\text{Var}(Y) =: \sigma_Y^2$  We assume they exist.

Def. The **covariance** of  $X$  and  $Y$  is defined by

$$\text{Cov}(X, Y) = E((X - \mu_X)(Y - \mu_Y)) = E(XY) - \sigma_X \sigma_Y$$

The **correlation** of  $X$  and  $Y$  is defined by

$$\rho_{XY} = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y} \in [-1, 1]$$

Lemma: If  $X$  and  $Y$  are independent then  $\text{Cov}(X, Y) = \rho_{XY} = 0$  easy exercise

⚠ The converse is not true.

The covariance measures a linear relationship:

$$|\rho_{XY}| = 1 \text{ iff } P(Y = aX + b) = 1 \exists a, b \in \mathbb{R}$$

The pages 3,4 in Appendix 3 are helpful and easy.

## II. Random sample

### II.1 Basic definitions

Def. A **random sample** of size  $N$  is a family of random variables

- 1) all having the same pdf continuous case or pmf discrete case and
- 2) all mutually independent.

We speak about **iid** random variables.

1) ↑ identically distributed

 The condition of independence is very strong;

We take it as a first approximation.

$$\Rightarrow f_{\underline{X}}(x_1, \dots, x_n) = f_{X_1}(x_1) \cdots f_{X_n}(x_n) \quad \text{because of independence}$$

Def. If  $Y: \mathbb{R}^N \mapsto \mathbb{R}^d$  is Borel measurable ( $\Leftarrow$  continuous)

then  $Y(X_1, \dots, X_N)$  is a real if  $d=1$  or vector if  $d>1$  valued random variable called a **statistic**. ↳ no dependence explicitly on other variables ( $\mu$ , etc)

### Examples

1) Sample mean:  $\bar{X} = \frac{1}{N} \sum_{j=1}^N X_j$

2) Sample variance:  $S^2 = \frac{1}{N-1} \sum_{j=1}^N (X_j - \bar{X})^2$

3) Sample standard deviation:  $S = \sqrt{S^2}$

Thm. Let  $\underline{X} = (X_1, \dots, X_N)$  be a random sample, with  $E(X_j) = \mu$  and  $\text{Var}(X_j) = \sigma^2$ .

Then  $E(\bar{X}) = \mu$ ;  $\text{Var}(\bar{X}) = \frac{\sigma^2}{N}$ ;  $E(S^2) = \sigma^2$  ↔ arbitrary ↔

(Thm 5.2.6)

A useful relation:  $M_{\bar{X}}(t) = (M_{X_i}(t/N))^N$  if  $M_{X_i}$  exist

### II.2 Sample from a normal distribution

Let  $X_1, \dots, X_N$  be <sup>id</sup> random sample with  $X_j \sim n(\mu, \sigma^2)$  Normal distribution of mean  $\mu$  and variance  $\sigma^2$

with the pdf of  $n(\mu, \sigma^2)$  given by ↑ having or following

$$f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

One has  $E(X_j) = \mu$  and  $\text{Var}(X_j) = \sigma^2$

### Propositions

1)  $\bar{X}$  and  $S^2$  are independent random variables (Thm 5.3.1)

2)  $\bar{X} \sim n(\mu, \sigma^2/N)$

3)  $(N-1)S^2/\sigma^2$  has a chi squared distribution with parameter  $N-1$ . ( $\chi_{N-1}^2$ )

Remark: If  $Y \sim n(\mu, \sigma^2)$ , then  $\frac{Y-\mu}{\sigma} \sim n(0,1)$  <sup>re-scaling</sup>. Thus

$$\frac{\bar{X}-\mu}{\sigma/\sqrt{N}} = \sqrt{N} \frac{\bar{X}-\mu}{\sigma} \sim n(0,1)$$

If we compute  $\sqrt{N} \frac{\bar{X}-\mu}{S} = \frac{(\bar{X}-\mu)/(\sigma/\sqrt{N})}{\sqrt{S^2/\sigma^2}} \rightarrow \sim n(0,1)$   
 $\rightarrow \sim \chi^2_{N-1}/N-1$

The ratio is the **student's distribution** ( $\equiv$  **t-distribution**) and does not depend on  $\sigma$ .

$\leadsto$  We can deduce  $\mu$ .

### II.3 Order statistics

Def. The **order statistics** of a random sample  $X_1, \dots, X_N$  are the sample values placed in ascending order:

$$X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(N)}$$

Examples:  $X_{(1)} = \min_{j \in \{1, \dots, N\}} X_j$ ;  $\dots$ ;  $X_{(N)} = \max_{j \in \{1, \dots, N\}} X_j$

Based on them one has

• **Sample range**:  $R := X_{(N)} - X_{(1)}$

• **Sample median**:  $M := \begin{cases} X_{(\frac{N+1}{2})} & \text{if } N \text{ odd} \\ \frac{1}{2}(X_{(N/2)} + X_{(N/2+1)}) & \text{if } N \text{ even} \end{cases}$

⚠ **Sample median  $\neq$  sample mean**

• For  $p \in (0,1)$  we define the **100p<sup>th</sup> sample percentile** to be the observation s.t.  $Np$  observations are smaller and  $N(1-p)$  are larger

$$= \begin{cases} X_{(\lfloor Np \rfloor)} & \text{if } \frac{1}{2N} < p < \frac{1}{2} \\ X_{(N+1-\lfloor N(1-p) \rfloor)} & \text{if } \frac{1}{2} < p < 1 - \frac{1}{2N} \end{cases} \text{ with } i - \frac{1}{2} \leq b < i + \frac{1}{2} \text{ with } i \in \mathbb{N} \Rightarrow \{b\} := i \text{ nearest integer}$$

One often uses

**lower quartile** := 25<sup>th</sup> sample percentile

**upper quartile** := 75<sup>th</sup> sample percentile

Computation related to  $X_{(j)}$

Prop. (discrete case)

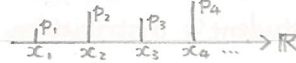
Suppose  $X_1, \dots, X_N$  are iid with  $X_j$  discrete with

$$\text{Ran}(X_j) = \{x_i\}_{i \in \mathbb{N}}$$

and s.t.  $x_i \leq x_{i+1}$  and  $f_{X_j}(x_i) =: p_i$  with  $\sum_{i \in \mathbb{N}} p_i = 1$ . Then

$$P(X_{(j)} \leq x_i) = \sum_{k=j}^N \binom{N}{k} p_i^k (1-p_i)^{N-k} \quad \text{with}$$

$$p_i = F_{X_j}(x_i) = P(X_j \leq x_i) = \sum_{k=1}^i p_k$$



Proof

Set  $Y := \# \{X_j \leq x_i \text{ for } j=1, \dots, N\}$  <sup>number</sup> of  $X_j$  taking a value smaller than  $x_i$ ;

But  $\{X_j\}$  are i.i.d and  $P(X_j \leq x_i) = p_i$

Then  $Y \sim \text{binomial}(N, p_i)$ .

Then  $\{X_{(j)} \leq x_i\} = \{Y \geq j\}$  <sup>key point</sup> (both are subsets of  $S \times \dots \times S$ )

$$\Rightarrow \underbrace{P(X_{(j)} \leq x_i)}_{\text{want to compute}} = P(Y \geq j) \quad \text{because of binomial}$$

$$= \sum_{k=j}^N P(Y=k) \stackrel{\downarrow}{=} \sum_{k=j}^N \binom{N}{k} p_i^k (1-p_i)^{N-k} \quad (*) \quad \square$$

Prop. (continuous case) (Thm. 5.4.4)

If  $X_j$  has cdf  $F$  and pdf  $f$ , then

$$f_{X_{(j)}}(x) = \frac{N!}{(j-1)!(N-j)!} f(x) F(x)^{j-1} (1-F(x))^{N-j}$$

<sup>pdf for having  $j$  r.v.  $X_k$  taking a value smaller than  $x$ .</sup>

## II.4 Computing with random samples

Aim: compute (\*) numerically with random samples.

Idea: use the **weak law of large number** (from Appendix 3).

Consider  $\underline{X}$  of i.i.d. r.v. with  $E(X_j) = \mu$  and  $\text{Var}(X_j) = \sigma^2$

Then  $\overline{X}_N = \frac{1}{N} \sum_{j=1}^N X_j$  (sample mean);

$\overline{X}_N \xrightarrow{N \rightarrow \infty} \mu$  in probability

$$\Leftrightarrow \forall \varepsilon > 0, P(|\overline{X}_N - \mu| \geq \varepsilon) \xrightarrow{N \rightarrow \infty} 0$$

1) Consider  $X_1, \dots, X_N$  discrete r.v. satisfying the prescribed distribution of the previous proposition.

2) Set  $Y_k := \begin{cases} 1 & \text{if at least } j \text{ } X_e \text{ take a value } \leq x_i \\ 0 & \text{otherwise} \end{cases}$

3) Observe that  $Y_k \sim \text{Bernoulli}(q)$  with

$$q = P(X_{(j)} \leq x_i), \text{ and } E(Y_k) = q$$

4) Then  $\{Y_k\}$  <sup>by repeating the experiment</sup> is an i.i.d family with  $E(Y_k) = q$ .

By weak law of large number,  $\bar{Y} \xrightarrow[\text{experiments}]{\text{for many}} q$

What is missing: how to generate random numbers following a prescribed distribution

There are solutions. See section 5.6 (exercise: report on this)

### III Data reduction

Idea: Suppose  $\underline{X}$  is a random sample with  $X_j \sim f(\cdot | \theta)$ , e.g.  $n(\mu, \sigma^2)$  <sup>← unknown parameter</sup> <sub>← certain distribution</sub> <sup>↑ θ</sup> <sub>↑ θ</sub> only interested in one parameter not in the others

Can we find a statistic  $T(\underline{X})$  which keeps all information on  $\theta$ ?

(with the aim of reducing the necessary information)

#### III.1 Sufficient statistics

Sufficient principle:  $T(\underline{X})$  is a sufficient statistic for  $\theta$  if

two sample points  $\underline{x}$  and  $\underline{y}$  with  $T(\underline{x}) = T(\underline{y})$  One gets same influence on  $\theta$ .

Def.  $T(\underline{X})$  is a sufficient statistic for  $\theta$  if

the conditional pmf or pdf of the sample  $\underline{X}$  given  $T(\underline{X})$  does not depend on  $\theta$ .

Example: Consider  $X_j \sim \text{Bernoulli}(\theta)$  with  $\theta \in (0, 1)$  and  $T(\underline{X}) := \sum_{j=1}^N X_j$  with  $N$  fixed.

e.g.  $\underline{x} = (0, 1, 0, 0, 0, 1, 1, 0, \dots, 1)$  e.g.  $T(\underline{x}) = 25$  <sup>number of 1 in  $\underline{x}$</sup>

Observe that  $T(\underline{X}) \sim \text{binomial}(N, \theta)$ .

Set  $t := \sum_{i=1}^N x_i$ . Then the conditional pmf of  $\underline{X}$  given  $T(\underline{X})$  is

$$\frac{\prod_{j=1}^N \text{Bern}(x_j | \theta)}{\text{binomial}(t | N, \theta)} = \frac{\prod_{j=1}^N \theta^{x_j} (1-\theta)^{1-x_j}}{\binom{N}{t} \theta^t (1-\theta)^{N-t}} = \frac{\theta^{\sum_{j=1}^N x_j} (1-\theta)^{\sum_{j=1}^N (1-x_j)}}{\binom{N}{t} \theta^t (1-\theta)^{N-t}} = \frac{\theta^t (1-\theta)^{N-t}}{\binom{N}{t} \theta^t (1-\theta)^{N-t}} = \frac{1}{\binom{N}{t}}$$

=  $\frac{1}{\binom{N}{t}}$  indep of  $\theta$ .

$\Rightarrow T$  is a sufficient statistics for  $\theta \Rightarrow$  any  $\underline{x}, \underline{y}$  with  $\sum x_j, \sum y_j$  provides the same information on  $\theta$ .

Thm. (Factorization Thm)

A statistic  $T(\underline{X})$  is sufficient for  $\theta$  if and only if

$$f_{\underline{X}}(\underline{x} | \theta) = g(T(\underline{x}) | \theta) h(\underline{x}) \quad \forall \underline{x} \in \mathbb{R}^N$$

<sup>← indep of  $\theta$</sup>

Example:  $X_j \sim (\mu, \sigma^2)$  and consider  $\theta = \mu$ .  $\sigma^2$  is known.

$$\begin{aligned} f_{\underline{X}}(\underline{x} | \mu, \sigma^2) &= \prod_{j=1}^N (2\pi\sigma^2)^{-\frac{1}{2}} \exp\left(-\frac{(x_j - \bar{x} + \bar{x} - \mu)^2}{2\sigma^2}\right) \quad \bar{x} := \frac{1}{N} \sum_{j=1}^N x_j \\ &= (2\pi\sigma^2)^{-\frac{N}{2}} \exp\left(-\frac{\sum_{j=1}^N (x_j - \bar{x})^2 + N(\bar{x} - \mu)^2}{2\sigma^2}\right) \\ &= \underbrace{e^{-N(\bar{x} - \mu)^2 / 2\sigma^2}}_{g(\bar{x} | \mu)} \underbrace{(2\pi\sigma^2)^{-\frac{N}{2}} e^{-\sum_{j=1}^N (x_j - \bar{x})^2 / 2\sigma^2}}_{\text{indep of } \mu} \end{aligned}$$

$\Rightarrow T(\underline{X}) := \bar{X}$  is a sufficient statistic for  $\mu$ .

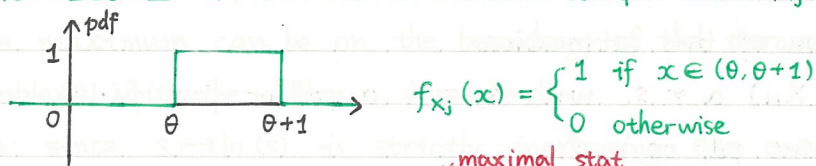
Remarks:

- 1) Sufficient statistics are  $\theta$ -dependent and model dependent ( $X_j$ ).
- 2) Vector valued  $T(\underline{X})$  and vector parameters  $\theta$  are possible.
- 3) We can look at minimal sufficient statistics. (maybe not unique)

(any other sufficient statistics should be a function of a minimal one)

Def. A statistic  $T(\underline{X})$  whose pdf or pmf does not depend on  $\theta$  is called an **ancillary statistic**.

Example: Let  $\underline{X} = (X_1, \dots, X_N)$  a random sample with  $X_j \sim \text{unif}(\theta, \theta+1)$  with



Then we set  $R(\underline{X})$  **range statistic** =  $X_{(N)} - X_{(1)}$

Then the pdf of  $R(\underline{X})$  is the function  $\uparrow$  **minimal stat.**

$$x \mapsto N(N-1)x^{N-2}(1-x) \text{ for } x \in (0,1) \quad \text{exercise: someone could show this.}$$

which is  $\theta$ -independent.

$\Rightarrow R(\underline{X})$  is an ancillary statistic.

⚠ A sufficient statistic can be related to an ancillary statistic.

Example: in the previous example,

$(R(\underline{X}), M(\underline{X}) := \frac{1}{2}(X_{(1)} + X_{(N)}))$  is a sufficient statistic for  $\theta$ .

It means that both information are necessary, and  $R(\underline{X})$  alone does not say anything on  $\theta$ .

### III.2 Likelihood principle

Def. Let  $\underline{X} := (X_1, \dots, X_N)$  be a r. sample with joint pdf or pmf  $f_{\underline{X}}(\cdot | \theta)$ .

For a given observation  $\underline{x}$ , the function

$$\theta \mapsto L(\theta | \underline{x}) := f_{\underline{X}}(\underline{x} | \theta)$$

is called the **likelihood function** at  $\underline{x}$ .

Likelihood principle

If  $\underline{x}$  and  $\underline{y}$  satisfy  $L(\theta | \underline{x}) = cL(\theta | \underline{y}) \forall \theta$  and a fixed  $c$ , then the inference on  $\theta$  from  $\underline{x}$  and  $\underline{y}$  should be the same.

Example: For  $\underline{X} = (X_1, \dots, X_N)$  with  $X_j \sim n(\mu, \sigma^2)$ , one has

$$f_{\underline{X}}(\underline{x} | \mu, \sigma^2) = e^{-N(\bar{x} - \mu)^2 / 2\sigma^2} (2\pi\sigma^2)^{-N/2} e^{-\sum_j (x_j - \bar{x})^2 / 2\sigma^2}$$

For  $\theta = \mu$ , one has

$$L(\theta | \underline{x}) = cL(\theta | \underline{y}) \text{ if } \bar{x} = \bar{y} \text{ and } c = \exp\left(\sum_j \frac{-(x_j - \bar{x})^2 + (y_j - \bar{y})^2}{2\sigma^2}\right)$$

Thus from this principle, if  $\bar{x} = \bar{y}$  the inference on  $\theta$  is same from  $\underline{x}$  or  $\underline{y}$ .

## IV Point estimation

Aim: infer expressions for some parameters  $\theta$  from a random sample  $\underline{X}$  or from a realized measurement  $\underline{x}$ .

2 parts: 1) finding estimation for  $\theta$  (several methods)  
2) evaluation of this estimations

Framework:  $\underline{X} = (X_1, \dots, X_N)$  a r. s. with  $X_j = X$  a pdf or pmf  $f(\cdot|\theta)$ .  
 $f_{\underline{X}}(\cdot|\theta)$  is the joint pdf or pmf.

### 1.1 Method of moments ( $k \in \mathbb{N}$ )

$$\mu_k := E(X^k) = \int_{\mathbb{R}} x^k f(x|\theta) dx$$

Set  $m_k := \frac{1}{N} \sum_{j=1}^N X_j^k$  and solve the system of equation

$$\begin{cases} m_1 = \mu_1 \\ m_2 = \mu_2 \\ \vdots \\ m_k = \mu_k \end{cases} \leftarrow \begin{array}{l} \text{depending on} \\ \text{the size of } \theta \end{array}$$

Example (used for estimating the crime rate)

$X_j = X \sim \text{binomial}(k, p)$  with  $k \in \mathbb{N}$ ,  $p \in (0, 1)$

$\uparrow$  number of crimes reported to the police every day  $\quad \uparrow$  reporting rate of crime "real" number of crime every day

$$\mu_1 = kp; \quad \mu_2 = kp(1-p) + kp^2 \quad (\text{from table})$$

$$\begin{cases} m_1 = \bar{X} & = kp \\ m_2 = \frac{1}{N} \sum_{j=1}^N X_j^2 & = kp(1-p) + kp^2 \end{cases}$$

The solution is

$$k = \frac{\bar{X}^2}{\bar{X} - \frac{1}{N} \sum_j (X_j - \bar{X})^2}; \quad p = \frac{\bar{X}}{k}$$

### 1.2 Maximum likelihood estimator (MLE)

Recall  $L(\theta|\underline{x}) = f_{\underline{X}}(\underline{x}|\theta)$

Def: For any fixed sample point  $\underline{x}$  let  $\hat{\theta}(\underline{x})$  be the point where  $\theta \mapsto L(\theta|\underline{x})$  takes its maximal value. There might be more than one. Then the maximum likelihood estimator for  $\theta$  on a sample  $\underline{X}$  is  $\hat{\theta}(\underline{X})$ .

Then given  $\underline{x}$  we estimate  $\theta$  by  $\hat{\theta}(\underline{x})$ .

Justification: The maximum likelihood estimator is the parameter point which is observed most likely by the sample.



Drawbacks:

- requires heavy computation (compute derivatives and study the Hessian matrix)
- not always unique
- the maximum can be on the boundary of the parameter space
- problems with the discrete parameters.

Remark: since  $s \mapsto \ln(s)$  is strictly increasing, one can also study  $\theta \mapsto \ln L(\theta | \underline{x})$  and get the same maximum.

One speaks about **log likelihood functions**.

Example

$$X_j \sim n(0, 1)$$

$$L(\theta | \underline{x}) = \frac{1}{(2\pi)^{N/2}} e^{-\frac{1}{2} \sum_{j=1}^N (x_j - \theta)^2}$$

One has

$$\frac{\partial}{\partial \theta} (\ln L(\theta | \underline{x})) = 0 \Leftrightarrow \sum_{j=1}^N (x_j - \theta) = 0 \Leftrightarrow \theta = \frac{1}{N} \sum_{j=1}^N x_j$$

and it turns out to be a maximum. Thus

$$\hat{\theta}(\underline{x}) = \frac{1}{N} \sum_{j=1}^N x_j$$

### 1.3 Bayes estimator

Idea: we suppose that  $\theta$  follows a certain prob. distribution

(called **prior distribution**) which is going to be updated with the sample to a **posterior distribution**. The update is based on **Bayes formula**.

Recall that Bayes formula reads:

If  $\{C_j\}$  is a partition of the sample space  $S (\Leftrightarrow \bigsqcup_j C_j = S)$  then

$$P(C_j | B) = \frac{P(B|C_j)P(C_j)}{\sum_k P(B|C_k)P(C_k)}$$

Example

Let  $\underline{X} = (X_1, \dots, X_N)$  a r.s. with  $X_j \sim \text{Bernoulli}(p)$  and suppose  $p \sim \text{beta}(\alpha, \beta)$   $p = \theta \in (0, 1)$  prior distribution

Set  $Y = \sum_{j=1}^N X_j \sim \text{binomial}(N, p)$  fixed

$P(C_j, B) \rightsquigarrow f(\theta | Y = y)$  posterior distribution

$$\frac{P(B|C_j)P(C_j)}{\sum_k P(B|C_k)P(C_k)} \rightsquigarrow \frac{\text{binomial}(y|N, p)\text{beta}(p|\alpha, \beta)}{\int \text{binomial}(y|N, s)\text{beta}(s|\alpha, \beta) ds}$$

This computation will be finished next week.

$$P(C_j) \rightsquigarrow \theta \mapsto \Pi(\theta) \quad \text{prior distribution}$$

$$P(C_j|B) \rightsquigarrow \theta \mapsto \Pi_{\text{post}}(\theta|Y=y) \quad \text{posterior distribution}$$

$$P(B|C_j) \rightsquigarrow y \mapsto f_Y(y|\theta)$$

$$\sum_k P(B|C_k) P(C_k) \rightsquigarrow y \mapsto \int f_Y(y|\theta) \Pi(\theta) d\theta$$

Suppose  $Y = \sum_{j=1}^N X_j \sim \text{binomial}(N, p)$

$$\Pi(p) \sim \text{beta}(\alpha, \beta) \quad \theta \in [0, 1]$$

fixed

$$\Rightarrow \Pi_{\text{post}}(p|y) = \frac{\text{binomial}(y|N, p) \text{beta}(p|\alpha, \beta)}{\int_0^1 \text{binomial}(y|N, s) \text{beta}(s|\alpha, \beta) ds} \quad \textcircled{1}$$

$$\textcircled{1} = \binom{N}{y} p^y (1-p)^{N-y} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{\alpha-1} (1-p)^{\beta-1}$$

$$= \binom{N}{y} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{y+\alpha-1} (1-p)^{N-y+\beta-1}$$

Gamma function:

$$\textcircled{2} = \int \textcircled{1} ds = \binom{N}{y} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} \frac{\Gamma(y+\alpha)\Gamma(N-y+\beta)}{\Gamma(N+\alpha+\beta)}$$

$$\Rightarrow \Pi_{\text{post}}(p|y) = \frac{\textcircled{1}}{\textcircled{2}} = \frac{\Gamma(N+\alpha+\beta)}{\Gamma(y+\alpha)\Gamma(N-y+\beta)} p^{y+\alpha-1} (1-p)^{N-y+\beta-1}$$

$$= \text{beta}(y+\alpha, N-y+\beta)(p)$$

By taking expectation of the prior and posterior distributions

$$E_{\text{prior}}(p) = \frac{\alpha}{\alpha+\beta}$$

$$E_{\text{post}}(p) = \frac{y+\alpha}{N+\alpha+\beta} = \frac{N}{\alpha+\beta+N} \frac{y}{N} + \frac{\alpha+\beta}{\alpha+\beta+N} \frac{\alpha}{\alpha+\beta} \rightarrow \text{estimation on } p \text{ without any prior idea}$$

The posterior expectation is a linear combination

of prior expectation and experimental expectation.

Remark: As  $N$  becoming large, the prior expectation is becoming less and less important

Remark: The linear combination is not an accident;

$\rightsquigarrow$  notion of **conjugate family** of a distribution.

## IV.2 Evaluating estimators

Different estimators for  $\theta$  can give you different values for  $\theta$ .

Which one should we choose?

## 2.1 Mean square error

Framework  $\underline{X} = (X_1, \dots, X_N)$  with  $X_j = X \sim f(\cdot | \theta)$ .

Let  $W = W(\underline{X})$  be an estimator ( $\equiv$  statistic) for  $\theta$ .

Def. The mean square error (MSE) of  $W$  is defined by

$$E((W - \theta)^2) \text{ still a function of } \theta$$

⚠ We made the choice of  $s \mapsto s^2$ . Later there will be a generation.

Observe that

$$\begin{aligned} E((W - \theta)^2) &= E((W - E(W) + E(W) - \theta)^2) \\ &= E((W - E(W))^2) + E(2(W - E(W))(E(W) - \theta)) + E((E(W) - \theta)^2) \\ &= \text{Var}_\theta(W) - (E_\theta(W) - \theta)^2 \end{aligned}$$

Def. If  $W$  is an estimator for  $\theta$ , we set

$$\text{Bias}_\theta(W) := E_\theta(W) - \theta$$

If  $\text{Bias}_\theta(W) = 0$  we say that  $W$  is unbiased.

$$\Rightarrow E_\theta((W - \theta)^2) = \text{Var}_\theta(W) + (\text{Bias}_\theta(W))^2$$

Remark: In Section II.1, we saw that if  $E(X) = \mu$  and  $\text{Var}(X) = \sigma^2$  then

$$\begin{aligned} E(\bar{X}) &= \mu \quad \text{and} \quad E(S^2) = \sigma^2 \\ \uparrow & \quad \quad \quad \uparrow \\ \text{sample mean} & \quad \quad \quad \text{sample variance} \end{aligned}$$

$\Rightarrow E(\bar{X})$  and  $E(S^2)$  are unbiased estimators for  $\mu$  and  $\sigma^2$  resp.

Now if  $X \sim n(\mu, \sigma^2)$  then  $E((\bar{X} - \mu)^2) = \text{Var}(\bar{X}) = \frac{\sigma^2}{N}$

$$\text{and } E((S^2 - \sigma^2)^2) = \frac{2}{N-1} \sigma^4$$

Question: Can we find better with a smaller MSE estimator for  $\mu$  and  $\sigma^2$ ?

Remark: for  $X \sim n(\mu, \sigma^2)$  consider

$$\tilde{S}^2 := \frac{1}{N} \sum_{j=1}^N (X_j - \bar{X})^2 = \frac{N-1}{N} S^2$$

$$\Rightarrow E(\tilde{S}^2) = \frac{N-1}{N} \sigma^2 \quad \Rightarrow \tilde{S}^2 \text{ is biased}$$

$$\text{But } E((\tilde{S}^2 - \sigma^2)^2) = \frac{2N-1}{N^2} \sigma^4 < \frac{2}{N-1} \sigma^4$$

$\Rightarrow \tilde{S}^2$  has a lower MSE, despite being biased.

~ Finding a better estimator is not a simple question.

We shall consider only unbiased estimators.

Def. An estimator  $W^*$  for  $\theta$  parameter with value unknown is the **best unbiased estimator** for  $\theta$  if  $\text{Var}_\theta(W^*) \leq \text{Var}_\theta(W)$  for any estimator  $W$  for  $\theta$  for any  $\theta$  value of parameter with  $W^*$  and  $W$  unbiased.

Thm. (7.3.19) The best unbiased estimator is unique if it exists.

*But it does not tell you how to find it.*

Question: Can we get  $\text{Var}_\theta(W) = 0$ ?

Thm. (7.3.9 + 7.3.10) (Cramer-Rao inequality) (based on Cauchy-Schwartz inequality)

$$\text{If } \frac{d}{d\theta} E_\theta(W) \equiv \frac{d}{d\theta} \int_{\mathbb{R}^N} W(x) f_x(x|\theta) dx = \int_{\mathbb{R}^N} \frac{\partial}{\partial \theta} [W(x) f_x(x|\theta)] dx$$

and  $\text{Var}_\theta(W) < \infty$  then  $\rightarrow = \theta$

$$\text{Var}_\theta(W) \geq \frac{\left( \frac{d}{d\theta} E_\theta(W) \right)^2}{N E_\theta \left[ \left( \frac{\partial}{\partial \theta} \ln f_x(\cdot|\theta) \right)^2 \right]} = 1$$

information number  
or Fisher information

If  $\text{Var}_\theta(W)$  saturates satisfies equality in this inequality,

then  $W$  is the best unbiased estimator for any value of  $\theta$ .

⚠ Otherwise for two  $W$  the  $\text{Var}_\theta(W)$  may cross.

Remark: The following relation holds:

$$\text{If } \frac{d}{d\theta} E \left( \frac{\partial}{\partial \theta} \ln f(\cdot|\theta) \right) = \int \frac{\partial}{\partial \theta} \left[ \frac{\partial}{\partial \theta} \ln f(\cdot|\theta) \right] f(x|\theta) dx \text{ then}$$

$$E_\theta \left[ \left( \frac{\partial}{\partial \theta} \ln f(\cdot|\theta) \right)^2 \right] = -E_\theta \left( \frac{\partial^2}{\partial \theta^2} \ln f(\cdot|\theta) \right)$$

## 2.2 Loss function optimality

So far,  $\text{MSE} = E((W-\theta)^2) = E(\mathcal{L}(W, \theta))$  with  $\mathcal{L}(s, \theta) = (s-\theta)^2$

but other function  $\mathcal{L} = \text{loss function}$  could be chosen. For example:

$$\cdot \mathcal{L}(s, \theta) = |s - \theta|$$

$$\cdot \mathcal{L}(s, \theta) = \frac{(s-\theta)^2}{|s|+1}$$

$$\cdot \mathcal{L}(s, \theta) = \begin{cases} (s-\theta)^2 & \text{for } s < \theta \\ 10(s-\theta)^2 & \text{for } s \geq \theta \end{cases}$$

$$\cdot \mathcal{L}(s, \theta) = \frac{s}{\theta} - 1 - \ln\left(\frac{s}{\theta}\right) \dots$$

Then the **risk function** is defined by  $R(\theta, W) := E(\mathcal{L}(W, \theta))$

and we want to have a value of  $R$  close to 0.

Remark: the nice feature  $E((W-\theta)^2) = \text{Var}(W) + \text{Bias}(W)^2$

will not be possible in general.

⇒ minimizing  $R(\theta, W)$  can be complicated for other function  $\mathcal{L}$ .

⇒ It is a complicated question.

## V Hypothesis test

Def. A **hypothesis** is a statement about a population of parameter!

Two complementary hypotheses are called the **null hypothesis** (denoted by  $H_0$ ) and the **alternative hypothesis** (denoted by  $H_1$ ).

Example: Let  $\Theta_0 \subset \Theta$  parameter space

$$H_0: \theta \in \Theta_0 \text{ and } H_1: \theta \in \underbrace{\Theta \setminus \Theta_0}_{\Theta_0^c}$$

Def. A **hypothesis test** is a rule which specifies for which values of  $\underline{x}$  the hypothesis  $H_0$  is accepted or rejected.

Def. The subset of the sample space for which  $H_0$  is rejected is denoted by  $\mathcal{R}$  and called the **rejection region**. More precisely:

$$\mathcal{R} = \{\underline{x} \mid H_0 \text{ is rejected based on } \underline{x}\}$$

Example: A hypothesis test consisting in checking if the statistic  $W(\underline{x}) \in [1, 3]$

(for example  $\bar{x} \in [1, 3]$ ) in which case we accept  $H_0$

(for example  $H_0: W(\underline{x}) = 1.5$ )  
"  $\theta$  "

### V.1 Finding tests

#### 1) Likelihood ratio test:

If  $\underline{X} = (X_1, \dots, X_N)$  with  $X_j \sim f(\cdot \mid \theta)$ , and recall that

$$L(\theta \mid \underline{x}) = f_{\underline{x}}(\underline{x} \mid \theta) = \prod_{j=1}^N f(x_j \mid \theta)$$

The **Likelihood ratio test (LRT)** for testing  $\theta \in \Theta_0 \subset \Theta$  consists in defining

$$\lambda(\underline{x}) = \frac{\sup_{\theta \in \Theta_0} L(\theta \mid \underline{x})}{\sup_{\theta \in \Theta} L(\theta \mid \underline{x})} \in [0, 1]$$

is big if  $\theta \in \Theta_0$  is likely

The rejection region is  $\mathcal{R} = \{\underline{x} \mid \lambda(\underline{x}) \leq c\}$  for a fixed  $c \in (0, 1)$ .

(recall  $H_0: \theta \in \Theta_0$ )

Example 1:  $X_j \sim n(\theta, 1)$ ,  $H_0: \theta = \theta_0$  given Then

$$\lambda(\underline{x}) = \frac{(2\pi)^{-\frac{N}{2}} \exp\left(-\sum_{j=1}^N (x_j - \theta_0)^2 / 2\right)}{(2\pi)^{-\frac{N}{2}} \exp\left(-\sum_{j=1}^N (x_j - \bar{x})^2 / 2\right)} = \exp\left(-N(\bar{x} - \theta_0)^2 / 2\right)$$

$$\lambda(\underline{x}) \leq c \Leftrightarrow -N(\bar{x} - \theta_0)^2 / 2 \leq \ln(c) \Leftrightarrow |\bar{x} - \theta_0| \geq \sqrt{-\frac{2}{N} \ln(c)}$$

Example 2: Suppose  $X_j \sim n(\mu, \sigma^2)$ ;  $H_0: \mu = \mu_0$  (given)

$$\lambda(\underline{x}) = \dots \leq c \Leftrightarrow \frac{\bar{x} - \mu_0}{S/\sqrt{N}} \geq c \quad (\text{computation done in Appendix 7})$$

$\downarrow$  unknown  
 $\downarrow$  sample variance  $\rightarrow$  follows a student t distribution

### 2) Bayesian test

$\rightsquigarrow$  prob. distribution for  $\theta$   
 Prior distribution  $\Pi$  for  $\theta$ , and we want to compute  $\Pi_{\text{post}}$  for  $\theta$ .

Then we are going to accept  $H_0: \theta \in \Theta_0$  if

$$P_{\text{post}}(\theta \in \Theta_0 | \underline{x}) = \int_{\Theta_0} \Pi_{\text{post}}(\theta | \underline{x}) d\theta \geq c$$

Example:  $X_j \sim n(\theta, \sigma^2)$ ;  $\Pi \sim n(\mu, J^2)$  with  $\sigma^2, \mu, J^2$  known.

$H_0: \theta \leq \theta_0$  fixed

$$\Pi_{\text{post}}(\cdot | \underline{x}) = \Pi_{\text{post}}(\cdot | \bar{x}) \stackrel{\text{Ex 7.22}}{\downarrow} n\left(\frac{NJ^2\bar{x} + \sigma^2\mu}{NJ^2 + \sigma^2}, \frac{\sigma^2J^2}{NJ^2 + \sigma^2}\right)$$

$\uparrow$  not an accident

If we choose  $c = \frac{1}{2}$ , we get by symmetry

$$P_{\text{post}}(\theta \leq \theta_0 | \underline{x}) \geq \frac{1}{2} \Leftrightarrow \frac{NJ^2\bar{x} + \sigma^2\mu}{NJ^2 + \sigma^2} \leq \theta_0$$

$$\Leftrightarrow \bar{x} \leq \theta_0 + \frac{\sigma^2(\theta_0 - \mu)}{NJ^2}$$

### 3) Union-intersection and intersection-union tests

Case 1:  $H_0: \theta \in \bigcap_{\gamma \in \Gamma} \Theta_{0,\gamma} \Rightarrow \mathcal{R} = \bigcup_{\gamma \in \Gamma} \mathcal{R}_\gamma$  (U.-I. test)

$\rightarrow$  family of condition

Case 2:  $H_0: \theta \in \bigcup_{\gamma \in \Gamma} \Theta_{0,\gamma} \Rightarrow \mathcal{R} = \bigcap_{\gamma \in \Gamma} \mathcal{R}_\gamma$  (I.-U. test)

### V.2 Evaluating the tests

Idea: evaluate the possible mistakes of a hypothesis test:

		Decision (on $\underline{x}$ )	
		accept $H_0$	reject $H_0$
"Truth"	$H_0$		Type-I error
	$H_1$	Type-II error	

If  $\theta \in \Theta_0$  and  $\mathcal{R}$  denotes the rejection region (for  $H_0$ ), then an error of type I takes place if  $\underline{x} \in \mathcal{R}$ . Its probability is  $P_\theta(\underline{x} \in \mathcal{R})$ . Conversely if  $\theta \in \Theta_0^c$ , the prob. of a type II error is  $1 - P_\theta(\underline{x} \in \mathcal{R})$ .

Def. The **power function** of a hypothesis test  $(c)$  with the rejection region  $R$  is

$$\beta: \theta \mapsto P_{\theta}(\underline{x} \in R)$$

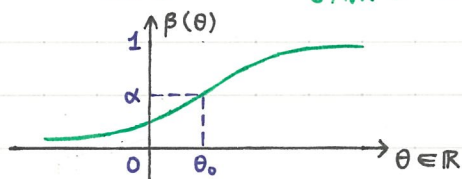
Ideal situation: if  $\theta \in \Theta_0$ ,  $\beta(\theta) \sim 0$

if  $\theta \in \Theta_0^c$ ,  $\beta(\theta) \sim 1$

Example:  $X_j \sim n(\theta, \sigma^2)$ ;  $H_0: \theta \leq \theta_0 \Leftrightarrow \Theta_0 = (-\infty, \theta_0]$

The hypothesis  $H_0$  is rejected if  $\frac{\bar{X} - \theta_0}{\sigma/\sqrt{N}} \geq c$ . Thus

$$\begin{aligned} \beta(\theta) &= P_{\theta} \left( \frac{\bar{X} - \theta_0}{\sigma/\sqrt{N}} \geq c \right) = P_{\theta} \left( \frac{\bar{X} - \theta}{\sigma/\sqrt{N}} \geq c + \frac{\theta_0 - \theta}{\sigma/\sqrt{N}} \right) \\ &= P_{\theta} \left( Z \geq c + \frac{\theta_0 - \theta}{\sigma/\sqrt{N}} \right) \text{ with } Z \sim n(0,1) \end{aligned}$$



with  $\alpha = P(Z \geq c)$

Experimenter's wish 1:

Error type I with prob  $\leq 0.1$

$$\Leftrightarrow \beta(\theta) \leq 0.1 \quad \forall \theta \leq \theta_0 \quad \Leftrightarrow \beta(\theta_0) = 0.1 \text{ since } \beta \text{ is increasing}$$

$$\Leftrightarrow P_{\theta} (Z \geq c) = 0.1 \quad \Leftrightarrow \underline{c = 1.28}$$

Experimenter's wish 2:

For  $\theta \geq \theta_0 + \sigma$ , Error of type II should have a prob.  $\leq 0.2$

$$\Leftrightarrow \beta(\theta_0 + \sigma) = 0.8$$

$$\Leftrightarrow P_{\theta} \left( Z \geq c + \frac{-\sigma}{\sigma/\sqrt{N}} \right) = 0.8 \quad \Leftrightarrow -0.84 \geq 1.28 - \sqrt{N}$$

$$\Leftrightarrow \underline{N \geq 5}$$

⚠ It is not always possible to adjust both errors.

We usually concentrate on error of type I.

Def. For any  $\alpha \in [0,1]$ , a test of power function  $\beta$

is a **size  $\alpha$ -test** if  $\sup_{\theta \in \Theta_0} \beta(\theta) = \alpha$ , and  
 is a **level  $\alpha$ -test** if  $\sup_{\theta \in \Theta_0} \beta(\theta) \leq \alpha$ .  
 } way to measure the prob. of type-I error.

Usually we fix  $\alpha = 0.05, 0.01$  or  $0.1$ . This provides an upper bound for type-I error

In example 1 of Section V.1 with

$$\underline{X} = (X_1, \dots, X_N), X_j \sim n(\theta, 1)$$

we obtained from the LRT that  $\lambda(x) \leq c \in (0, 1) \Leftrightarrow$

$$\sqrt{-2 \ln(c)} \leq \left| \frac{\bar{x} - \theta_0}{1/\sqrt{N}} \right| \sim n(0, 1) \text{ for}$$

$H_0: \theta = \theta_0$  for a fixed  $\theta_0$ .

Thus, if we set  $Z \sim n(0, 1)$  and  $P(Z \geq z_{\alpha/2}) \stackrel{\text{def}}{=} \frac{\alpha}{2}$

Thus, we can look for  $z_{\alpha/2}$  s.t.  $P(Z \geq \sqrt{-2 \ln(c)}) = \frac{\alpha}{2}$

$$\Leftrightarrow \sqrt{-2 \ln(c)} = z_{\alpha/2} \quad \left( \begin{array}{l} \text{given by tables} \\ \Leftrightarrow P(|Z| \geq \sqrt{-2 \ln(c)}) = \alpha \end{array} \right)$$

$$\Leftrightarrow c = e^{-z_{\alpha/2}^2/2}$$

$\leadsto$  a level- $\alpha$  test

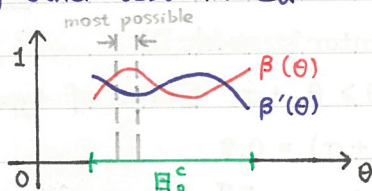
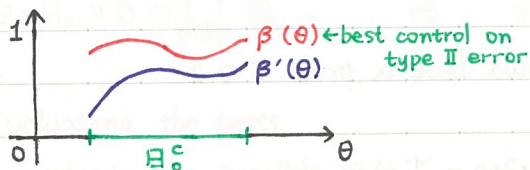
Def. Let  $C_\alpha$  be the set of all level- $\alpha$  tests for an level- $\alpha$  test  $H_0$ .

A test in  $C_\alpha$  is the **uniformly most powerful (UMP)**  $C_\alpha$ -test

if the corresponding power function  $\beta$  satisfies

$$\beta(\theta) \geq \beta'(\theta) \text{ for any } \theta \in \Theta_0^c \text{ and}$$

for the power function  $\beta'$  of any other test in  $C_\alpha$



Remark. Since different power function can cross,

it is rarely possible to define the UMP  $C_\alpha$ -test. 2 solutions:

- 1) Further divide  $\Theta_0^c$  and take the UMP  $C_\alpha$ -test on each part;
- 2) The plausible part of  $\Theta_0^c$  is neglected.



### V.3 p-values ( $\equiv$ statistical significance)

$\rightsquigarrow$  give less arbitrariness to the value  $c$

Aim: A p-value reports the result of a test on a more continuous scale rather than "accept  $H_0$ ." or "reject  $H_0$ ."

Def: Consider  $H_0: \theta \in \Theta_0$  and  $H_1: \theta \in \Theta_0^c$  and let  $W(X)$  be a (test) statistic such that larges values of  $W(X)$  give evidence that  $H_1$  is true.

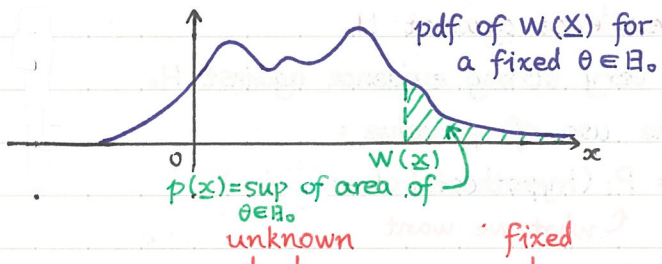
(for example  $W(X) = |X - \theta|$ ) For any  $x$  we set

$$p(x) := \sup_{\theta \in \Theta_0} P_{\theta}(W(X) \geq W(x)) \in [0, 1]$$

Then we consider  $p(x)$  and call it a **p-value** (for  $W(X)$ ).

Remarks:

- 1)  $p(X)$  is a random variable.
- 2) Given  $x$ ,  $p(x)$  gives the probability of equal or more extreme values of  $W(X)$ , knowing that  $H_0$  is true.  $\Leftrightarrow \theta \in \Theta_0$ .



Example 1:  $X_j \sim n(\mu, \sigma^2)$ ,  $H_0: \mu = \mu_0$  and  $\sigma^2$  arbitrary.

Set  $W(X) := \frac{|\bar{X} - \mu_0|}{s/\sqrt{N}}$  for which large values give evidence of  $H_1$ .  $E(\bar{X}) = \mu$  and which follows a [student t-distribution] with parameter  $N-1$  indep. of  $\sigma^2$ .

$$p(x) = \sup_{\substack{\mu \in \mathbb{R} \\ \sigma^2 \in \mathbb{R}}} P(W(X) \geq \frac{|\bar{x} - \mu_0|}{s/\sqrt{N}}) = 2P(T_{N-1} \geq \frac{|\bar{x} - \mu_0|}{s/\sqrt{N}})$$

because of abs. and symmetry      student T dist.      found in tables

Example 2:  $X_j \sim n(\mu, \sigma^2)$ ,  $H_0: \mu \leq \mu_0 \Leftrightarrow \mu \in \Theta_0 := (-\infty, \mu_0]$

Again  $W(X) := \frac{\bar{X} - \mu_0}{s/\sqrt{N}}$  with the property on  $W(X)$  satisfied. Then

$$\Rightarrow p(x) = \sup_{\substack{\mu \leq \mu_0 \\ \sigma^2 \geq 0}} P(W(X) \geq W(x)) = \sup_{\dots} P\left(\frac{\bar{X} - \mu_0 + \mu - \mu}{s/\sqrt{N}} \geq W(x)\right)$$

$$= \sup P\left(\frac{\bar{X} - \mu}{s/\sqrt{N}} \geq W(x) + \frac{\mu_0 - \mu}{s/\sqrt{N}}\right) = \sup P\left(\underbrace{\frac{\bar{X} - \mu}{s/\sqrt{N}}}_{\sim T_{N-1}} \geq \frac{\bar{x} - \mu_0}{s/\sqrt{N}} + \frac{W(x)}{s/\sqrt{N}}\right)$$

## Remark

Here, all computations were explicit, but it is not always the case.

In general, it is not so explicit but a computer can compute  $p(\underline{x})$  easily.

Interpretation ( $p(\underline{x}) \in [0, 1]$ )

The  $p$ -value  $p(\underline{x})$  should be interpreted in terms of repetition of the same experiment.  $p(\underline{x})$  gives the prob. that the new value  $W(\underline{x}')$  will be further away in the prob. distribution of  $W(\underline{X})$ , assuming that  $H_0$  is correct.

$p$  interpretation

$p > 0.1$  No evidence against  $H_0$ .

$\Rightarrow$  the data appear to be consistent with  $H_0$ .

$0.05 < p \leq 0.1$  weak evidence against  $H_0$ .

$0.01 < p \leq 0.05$  moderate evidence against  $H_0$ .

$p < 0.01$  strong or very strong evidence against  $H_0$ .

⚠ many controversies about the use of  $p$ -value :

$P_i$  (observation | hypothesis)  $\neq$   $P_i$  (hypothesis | observation)

$\uparrow$   $p$ -value

$\uparrow$  what we want

Example: Roll a dice

$H_0$ : the dice is fair (same prob of  $\frac{1}{6}$  for each face)

$\underline{X} = (X_1, \dots, X_N)$ ,  $X_j =$  discrete unif. dist.  $\{1, 2, \dots, 6\}$

$$W(\underline{X}) = \left| \frac{1}{N} \sum_{j=1}^N X_j - 3.5 \right| = |\bar{X} - 3.5|$$

large values of  $W(\underline{X})$  gives evidence of  $H_1$

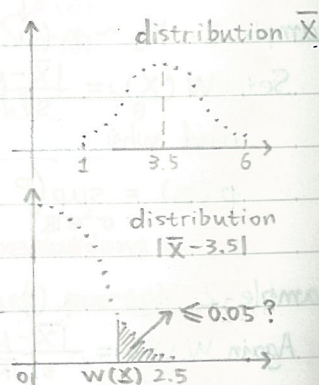
If the surface of the shade is smaller than 0.05

then we reject  $H_0$ , which means that

we consider that the dice is not fair.

Remark: it is a rather weak approach.

And if  $H_0$  is rejected, it does not say anything on the dice.



## VI Interval estimation

(linked to hypothesis test)

Interval estimation covers several related notions:

- • confidence intervals
- credible intervals (Bayes approach)
- likelihood intervals
- tolerance intervals

### VI.1 Confidence intervals

Def: A **confidence interval** for a parameter  $\theta$  is a pair of statistics

$L(X), U(X)$  with  $L(X) < U(X)$  (Lower & Upper)

together with a **confidence coefficient**  $\gamma$  given by

$$\gamma := \inf_{\theta} P(\theta \in [L(X), U(X)])$$

we always take the worst scenario.

↙ if there exists additional parameters, we also take the infimum on them

Remarks:

- One can accept that  $L(X) = -\infty$  and  $U(X) = +\infty$  but not both.
- Usually  $\gamma$  is denoted by  $1-\alpha$  and we speak about a  **$(1-\alpha)$  confidence**.

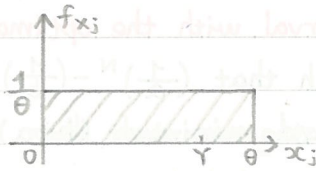
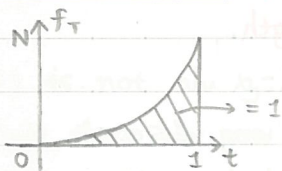
Example:

Let  $X = (X_1, \dots, X_N)$  with  $X_j \sim \text{uniform}(0, \theta)$

Let  $Y := \max\{X_1, \dots, X_N\} = X_{(N)}$  last ordered statistics and set  $T := \frac{Y}{\theta}$

What is the distribution of  $T$ ?  $T$  has a distribution  $f_T$  with

$f_T(t) = Nt^{N-1}$  for  $t \in [0, 1]$  (exercise based on § II.3)



Let us consider 2 possible confidence coefficients:

1)  $[L(X), U(X)] = [aY, bY]$  for  $1 \leq a < b$

2)  $[L(X), U(X)] = [Y+c, Y+d]$  for  $0 \leq c < d$

For 1)

$$P(\theta \in [aY, bY]) = P(aY \leq \theta \leq bY) = P(a \leq \frac{\theta}{Y} \leq b)$$

$$= P(\frac{1}{b} \leq \frac{Y}{\theta} \leq \frac{1}{a}) = \int_{1/b}^{1/a} Nt^{N-1} dt = (\frac{1}{a})^N - (\frac{1}{b})^N$$

$$\inf_{\theta} P(\theta \in [aY, bY]) = (\frac{1}{a})^N - (\frac{1}{b})^N \quad \text{no dependence on } \theta!$$

For 2)

$$P(\theta \in [Y+c, Y+d]) = P(Y+c \leq \theta \leq Y+d)$$

$$= P(1 - \frac{d}{\theta} \leq \frac{Y}{\theta} \leq 1 - \frac{c}{\theta}) = \int_{1-d/\theta}^{1-c/\theta} Nt^{N-1} dt = (1 - \frac{c}{\theta})^N - (1 - \frac{d}{\theta})^N$$

$$\inf_{\theta} P(\theta \in [Y+c, Y+d]) = \inf_{\theta} ((1 - \frac{c}{\theta})^N - (1 - \frac{d}{\theta})^N) = 0$$

The 2<sup>nd</sup> choice is not really good

since for any  $c$  and  $d$ , the confident coefficient is 0.

For 1), if we impose that

$$(\frac{1}{a})^N - (\frac{1}{b})^N = 1 - \alpha \quad \text{for a given } \alpha,$$

we can find some  $a$  and  $b$ .

no uniqueness: different possible choices for  $(a, b)$

Def. A random variable  $Q(X, \theta)$  this is not a statistic (explicit dependence on  $\theta$ ) is called a **pivotal quantity** or a **pivot** if its distribution function does not depend on  $\theta$ .

Example:  $\frac{Y}{\theta}$

Def. Among all statistics  $L(X), U(X)$  satisfying (fixed)

$$L(X) < U(X) \quad \text{and} \quad \inf_{\theta} P(\theta \in [L(X), U(X)]) = 1 - \alpha$$

the ones having the shortest length  $U(X) - L(X)$  define the  $(1 - \alpha)$ -confidence interval with the optimal length.

Exercise: find  $a$  and  $b$  such that

$$(\frac{1}{a})^N - (\frac{1}{b})^N = 1 - \alpha \quad \text{and} \quad \text{minimum } (b - a)? \quad \text{among } 1 \leq a < b$$

## VI.2 Relation with hypothesis test

Example: Suppose  $X_j \sim n(\mu, \sigma^2)$  and  $H_0: \mu = \mu_0$  <sup>given</sup>

Test: rejecting  $H_0$  if  $\left| \frac{\bar{X} - \mu_0}{\sigma/\sqrt{N}} \right| = |Z| \geq Z_{\alpha/2}$  with  $P(|Z| \geq Z_{\alpha/2}) = \frac{\alpha}{2}$

$\Rightarrow$  This test is an  $\alpha$ -level test.

$$\Leftrightarrow \text{Accept } H_0 \text{ if } \left| \frac{\bar{X} - \mu_0}{\sigma/\sqrt{N}} \right| < Z_{\alpha/2}$$

$$\Leftrightarrow -Z_{\alpha/2} < \frac{\bar{X} - \mu_0}{\sigma/\sqrt{N}} < Z_{\alpha/2}$$

$$\Leftrightarrow \bar{X} - Z_{\alpha/2} \frac{\sigma}{\sqrt{N}} < \mu_0 < \bar{X} + Z_{\alpha/2} \frac{\sigma}{\sqrt{N}} \text{ with}$$

$$P\left(\bar{X} - Z_{\alpha/2} \frac{\sigma}{\sqrt{N}} < \mu_0 < \bar{X} + Z_{\alpha/2} \frac{\sigma}{\sqrt{N}} \mid \mu = \mu_0\right) \stackrel{\text{true for any } \mu_0}{\downarrow} = 1 - \alpha$$

$$\Leftrightarrow P\left(\bar{X} - Z_{\alpha/2} \frac{\sigma}{\sqrt{N}} < \mu < \bar{X} + Z_{\alpha/2} \frac{\sigma}{\sqrt{N}}\right) = 1 - \alpha$$

$$\Leftrightarrow P\left(\mu \in \left[\bar{X} - Z_{\alpha/2} \frac{\sigma}{\sqrt{N}}, \bar{X} + Z_{\alpha/2} \frac{\sigma}{\sqrt{N}}\right]\right) = 1 - \alpha$$

Thus, we have obtained a  $(1-\alpha)$  confidence interval from a hypothesis test.

More generally:  $\subset \mathbb{R}$

Thm. For any  $\theta \in \Theta$  <sup>parameter space</sup> set  $H_0: \theta = \theta_0$  and consider a level  $\alpha$ -test  $\mathcal{T}_{\theta_0}$  for  $H_0$ .

Let  $\mathcal{A}(\theta_0) = \{\underline{x} \mid \mathcal{T}_{\theta_0}(\underline{x}) = H_0 \text{ accepted}\}$  be the acceptance region of this test (the complement of the rejection region).

For any  $\underline{x}$ , set

$$C(\underline{x}) := \{\theta \in \Theta \mid \underline{x} \in \mathcal{A}(\theta)\}$$

Then  $C(\underline{x})$  is a  $(1-\alpha)$  confidence set.

[Thm. 9.2.2] proof not long

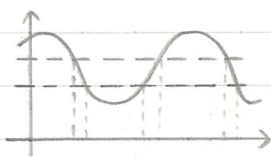
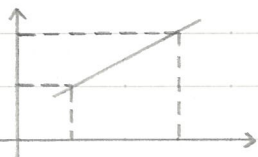
Remark:

1)  $C(\underline{x})$  is not always an interval

(but there are conditions such that one gets an interval)

2) It is possible to look for an optimal balance

between the confident coefficient and the length of  $C(\underline{x})$ .



## VII Asymptotic evaluation (let $N \rightarrow \infty$ )

### VII.1: Consistency, sufficiency, and robustness

We shall consider a family of estimators (= statistics)  $\{W_n\}_{n \in \mathbb{N}}$  with  $W_j = W_j(X_1, X_2, \dots, X_j)$

$$\sim f(\cdot | \theta)$$

Example:  $W_1 = X_1$ ,  $W_2 = \frac{1}{2}(X_1 + X_2)$ ,  $W_3 = \frac{1}{3}(X_1 + X_2 + X_3) \dots$

$$\bar{X}_n := W_n = \frac{1}{n} \sum_{j=1}^n X_j$$

Def. A sequence of estimators  $\{W_n\}_{n \in \mathbb{N}}$ , with  $W_j = W_j(X_1, X_2, \dots, X_j)$ , is a **consistent sequence** for the parameter  $\theta$  if

$$\forall \varepsilon > 0 \forall \theta \in \Theta: \lim_{n \rightarrow \infty} P(|W_n - \theta| < \varepsilon) = 1$$

$$\Leftrightarrow \lim_{n \rightarrow \infty} P(|W_n - \theta| \geq \varepsilon) = 0$$

similar to "convergence in probability"

Example:  $X_j \sim n(\theta, 1)$  and  $W_n = \bar{X}_n = \frac{1}{n} \sum_{j=1}^n X_j$

Recall that  $\frac{\bar{X}_n - \theta}{1/\sqrt{n}} \sim n(0, 1) \Rightarrow \bar{X}_n \sim n(\theta, \frac{1}{n})$

$$\begin{aligned} P(|\bar{X}_n - \theta| < \varepsilon) &= \int_{\theta - \varepsilon}^{\theta + \varepsilon} \left(\frac{n}{2\pi}\right)^{\frac{1}{2}} e^{-\frac{n}{2}(s - \theta)^2} ds \\ \frac{s - \theta = t}{\sqrt{n}t = x} &\int_{-\varepsilon}^{\varepsilon} \left(\frac{n}{2\pi}\right)^{\frac{1}{2}} e^{-\frac{n}{2}t^2} dt \\ &\int_{-\varepsilon\sqrt{n}}^{\varepsilon\sqrt{n}} \left(\frac{1}{2\pi}\right)^{\frac{1}{2}} e^{-\frac{x^2}{2}} dx \\ \frac{n \rightarrow \infty}{\varepsilon \text{ fixed}} &\rightarrow 1 \end{aligned}$$

Remark: We cannot do these computations <sup>always</sup> so explicitly, but we're lucky!  $\smile$

$$P(|W_n - \theta| < \varepsilon) = P((W_n - \theta)^2 < \varepsilon^2) \quad (\text{Appendix 3})$$

$$\stackrel{\text{Markov inequality}}{\leq} \frac{E((W_n - \theta)^2)}{\varepsilon^2} = \frac{1}{\varepsilon^2} (\text{Bias}_\theta(W_n)^2 + \text{Var}_\theta(W_n))$$

↑  
see IV.2

Thm. If for  $\theta \in \Theta$  and if

$$\lim_{n \rightarrow \infty} \text{Bias}_\theta(W_n) = 0 \text{ and } \lim_{n \rightarrow \infty} \text{Var}_\theta(W_n) = 0$$

Then  $\{W_n\}$  is a consistent family for  $\theta$ .

Corollary: If  $\underline{X} = (X_1, X_2, \dots)$  with  $E(X_j) = \theta < \infty$  and  $\text{Var}(X_j) < \infty$ ,

then  $\bar{X}_n$  is a consistent sequence of estimator for  $\theta$ .

(Based on §II.1)

What about efficiency? It is measured with variance.

Def. Let  $\{W_n\}$  be a sequence of estimators for  $\theta$ , and

let  $\{k_n\}$  be a natural family of scaling parameters. Natural = coming from other reasons e.g.  $k_n = \sqrt{n}$

1) If  $\lim_{n \rightarrow \infty} k_n \text{Var}(W_n) = J^2$  then  $J^2$  is called the **limiting variance**.

2) If  $k_n (W_n - \theta) \xrightarrow[\text{in distribution}]{n \rightarrow \infty} n(0, \sigma^2)$ , then  $\sigma^2$  is called the **asymptotic variance**.

↑ Recall in App. 3

$$\forall x \in \mathbb{R}: F_n(x) \xrightarrow{n \rightarrow \infty} \frac{1}{\sqrt{2\pi}\sigma} \int_{-\infty}^x e^{-\frac{s^2}{2\sigma^2}} ds$$

↑ cdf of  $k_n (W_n - \theta)$

Remark:  $J^2 = \sigma^2$  in general but not always. (See example 10.1.10)

The asymptotic parameter  $\sigma$  will be a measurement of the efficiency.

Question: Is there a "best"  $\sigma^2$ ?

Def.  $\{W_n\}_{n \in \mathbb{N}}$  is **asymptotically efficient** to  $\theta$  if

$$\sqrt{n} (W_n - \theta) \xrightarrow[\text{in distribution}]{n \rightarrow \infty} n(0, v(\theta)) \text{ with}$$

$$v(\theta) := \frac{1}{E_{\theta} \left( \left( \frac{\partial}{\partial \theta} \ln(f(\cdot|\theta)) \right)^2 \right)}$$

← related to Cramer-Rao bound (see 10.6.2)

Thm. If  $X_j \sim f(\cdot|\theta)$  with  $f(\cdot|\theta)$  satisfying some **weak technical assumption**

and if  $\hat{\theta}_n(X_1, \dots, X_n)$  is the maximum likelihood estimator for  $\theta$ ,

then  $\{\hat{\theta}_n\}$  is a consistent and asymptotically efficient family of estimators.

Maximum likelihood estimator: see §IV.2

Likelihood function  $\theta \mapsto L(\theta|x) := f(x|\theta)$  and look for its global maximum

Def. If  $\{W_n\}$  and  $\{V_n\}$  are 2 sequences of estimators for  $\theta$  satisfying

$$\sqrt{n} (W_n - \theta) \xrightarrow[\text{in distr.}]{n \rightarrow \infty} n(0, \sigma_W^2) \text{ and}$$

$$\sqrt{n} (V_n - \theta) \xrightarrow[\text{in distr.}]{n \rightarrow \infty} n(0, \sigma_V^2)$$

then the **asymptotic relative efficiency (ARE)** of  $\{V_n\}$  with respect to  $\{W_n\}$  is

$$\text{ARE}(\{V_n\}, \{W_n\}) := \frac{\sigma_W^2}{\sigma_V^2}$$

Remark:  $\frac{v(\theta)}{\sigma_V^2} \leq 1$

We should look for a sequence of estimators such that this ratio is close to 1.

Question: Is there always a sequence of estimators with the best  $\sigma^2$ ?

Unfortunately no.

What about robustness? (See the Appendix 10)

Idea: What happens if  $X_j \neq f(\cdot|\theta)$  for some  $j$  (rare events)?

Based on this idea, there should be a trade-off between efficiency & robustness.

→ many books.

Example: Consider the sample  $\{1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 100\}$

Outlier: a point that differs a lot from the others ↗

Then sample mean  $\bar{x} \approx 14$  not robust

sample median = 6 more robust

If we compute the ARE

(If the pdf  $f$  is symmetric  $\Rightarrow$  median = mean)

$$\text{ARE}(\underset{\otimes}{\text{median}}, \underset{\uparrow}{\text{mean}}) = \begin{cases} 0.64 & \text{normal} \\ 0.82 & \text{logistic} \\ 2 & \text{double exponential} \end{cases}$$

based on  $\bar{X}_n$

$\otimes$  define  $M_n :=$  median for a sample  $(X_1, \dots, X_n)$

and then  $\sqrt{n}(M_n - \theta) \xrightarrow[n \rightarrow \infty]{\text{in distr.}} N(0, \sigma_{\text{median}}^2)$

Then for normal and logistic distributions, mean has a more efficient behavior;

for double exponential distribution, median is more efficient.

↑ because of heavy tail

One way to take the best of both sequences of estimation is

to consider a mixture:

Consider  $\sum_{j=1}^n p(X_j - a)$  and  $p(x) = \begin{cases} \frac{1}{2} x^2 & \text{if } |x| \leq k \\ k|x| - \frac{1}{2} k^2 & \text{if } |x| \geq k \end{cases}$  related to mean  
and set  $\hat{\theta}_n(X_1, \dots, X_n)$  for the related to median

minimizer (as a function of  $a$ ) of this expression.

$k$  is a parameter that can be fixed freely.

With this new sequence of estimators we can compute (for  $k = 1.5$ )

	normal	logistic	d.exp
ARE (new, mean)	0.96	1.08	1.37
ARE (new, median)	1.51	1.31	0.68

↖ stable ↗      ← new is an improvement

Conclusion:  $\{\hat{\theta}_n\}$  is a balance between mean and median, but is more robust.

( $n \rightarrow \infty$ )



### VIII Analysis of variance and regression

#### VIII.1 "One way" ANOVA

Idea: Consider data like

	<u>Treatments</u>				
	1	2	...	k	
Observation ↓	$y_{11}$	$y_{21}$		$y_{k1}$	We shall assume that the corresponding r.v. follow unknown noise or error $Y_{ij} = \theta_i + \epsilon_{ij}$ $i = 1, \dots, k$ $j = 1, \dots, n_i$
	$y_{12}$	$y_{22}$		$y_{k2}$	
	$\vdots$	$\vdots$		$\vdots$	
	$y_{1n_i}$	$y_{2n_i}$		$y_{kn_i}$	

with  $\{\epsilon_{ij}\}$  independent.

Remark: we could consider

$$Y_{ij} = \mu + J_i + \epsilon_{ij}$$

but usually <sup>additional parameter</sup> impose that  $\sum_{i=1}^k J_i = 0$  which fixes one parameter.

Def. The model  $Y_{ij} = \theta_i + \epsilon_{ij}$  is called a **oneway ANOVA** if

- 1)  $\epsilon_{ij}$  is a r.v. following  $n(0, \sigma^2)$   <sup>$\sigma$  is independent of  $i, j$</sup>  for any  $i, j$ .
- 2)  $\epsilon_{ij}$  and  $\epsilon_{i'j'}$  are independent for any  $(i, j) \neq (i', j')$ .

Remark: These assumptions can also be weakened if necessary.

Def. **ANOVA null assumption** is  $H_0: \theta_1 = \theta_2 = \dots = \theta_k$ . <sup>very strong assumption</sup>

$$\Rightarrow H_1: \theta_j \neq \theta_k \text{ for } \geq 1 \text{ pair } (\theta_j, \theta_k) \text{ with } j \neq k$$

Let us set

$$A = \mathcal{A}_k = \{ \underline{a} = (a_1, a_2, \dots, a_k) \in \mathbb{R}^k \text{ with } \sum_{j=1}^k a_j = 0 \}$$

Examples:  $\underline{a} = (1, -1, 0, \dots, 0)$  or  $\underline{a} = (1, -\frac{1}{2}, -\frac{1}{2}, 0, \dots, 0)$ , etc

Def. Consider  $\underline{t} := (t_1, \dots, t_k)$  a set of  $k$  parameters or of  $k$  r.v.

If  $\underline{a} \in \mathcal{A}_k$ , then  $\sum_{j=1}^k a_j t_j \equiv \underline{a} \cdot \underline{t}$  is called a **contrast**.

Lemma:  $H_0 \Leftrightarrow \forall \underline{a} \in \mathcal{A}: \underline{a} \cdot \underline{\theta} = 0$    
  $\Rightarrow$  easy   
  $\Leftarrow$  as an exercise

Corollary:  $H_1 \Leftrightarrow \exists \underline{a} \in \mathcal{A}: \underline{a} \cdot \underline{\theta} \neq 0$

Under the ANOVA assumption one has

$$Y_{ij} \sim n(\theta_i, \sigma^2) \quad \forall i = 1, \dots, k, \quad \forall j = 1, \dots, n_i$$

$$\Rightarrow \bar{Y}_i := \frac{1}{n_i} \sum_{j=1}^{n_i} Y_{ij} \sim n(\theta_i, \frac{\sigma^2}{n_i})$$

Then for any  $\underline{a} \in \mathbb{R}^k$  consider  $\sum_{i=1}^k a_i \bar{Y}_i =: \underline{a} \cdot \bar{\mathbf{Y}}$  one has

$$\underline{a} \cdot \bar{\mathbf{Y}} \sim n\left(\sum_{i=1}^n a_i \theta_i, \sigma^2 \sum_{i=1}^k \frac{a_i^2}{n_i}\right) \quad (\text{Ex. 11.8})$$

If  $\sigma^2$  is not known, then we can define the sample variance

$$s_i^2 = \frac{1}{n_i - 1} \sum_{j=1}^{n_i} (Y_{ij} - \bar{Y}_i)^2 \sim \chi_{n_i - 1}^2 \quad (\S II.2)$$

Since  $\sigma^2$  is the same for all experiments, one can set

$$s^2 = \frac{1}{N-k} \sum_{i=1}^k (n_i - 1) s_i^2 = \frac{1}{N-k} \sum_{i=1}^k \sum_{j=1}^{n_i} (Y_{ij} - \bar{Y}_i)^2 \text{ and}$$

$$(N-k) s^2 / \sigma^2 \sim \chi_{N-k}^2 \quad \text{sum of } \chi_{n_i-1}^2 \text{ (Lemma 5.3.2) with}$$

$$N := \sum_{i=1}^k n_i$$

Then  $\frac{\sum_{i=1}^k a_i \bar{Y}_i - \sum_{i=1}^k a_i \theta_i}{\sqrt{s^2 \sum_{i=1}^k \frac{a_i^2}{n_i}}} \sim t_{N-k}$

Now for any  $\underline{a} \in \mathbb{R}^k$  fixed, a hypothesis test could be

Reject  $H_0: \sum_{i=1}^k a_i \theta_i = 0$  if  $\left| \frac{\underline{a} \cdot \bar{Y} - \underline{a} \cdot \underline{\theta}}{\sqrt{s^2 \sum_{i=1}^k \frac{a_i^2}{n_i}}} \right| > t_{N-k, \frac{\alpha}{2}}$  for a given  $\alpha$ .

Equivalently,

$\alpha$  confident interval with confidence coefficient  $1-\alpha$  is given by

$$\sum_{i=1}^k a_i \bar{y}_i - t_{N-k, \frac{\alpha}{2}} \sqrt{s^2 \sum_{i=1}^k \frac{a_i^2}{n_i}} \leq \sum_{i=1}^k a_i \theta_i \leq \sum_{i=1}^k a_i \bar{y}_i + t_{N-k, \frac{\alpha}{2}} \sqrt{s^2 \sum_{i=1}^k \frac{a_i^2}{n_i}}$$

Key fact: If we choose  $\underline{a} = (1, -1, 0, \dots, 0)$  then we are testing  $H_0: \theta_1 - \theta_2 = 0$

or for  $\underline{a} = (1, -\frac{1}{2}, -\frac{1}{2}, 0, \dots, 0)$  then we are testing  $H_0: \theta_1 = \frac{1}{2}(\theta_2 + \theta_3)$ .

Observe that all data are used for the computation of  $s^2$ .

⚠ If we choose 2 different  $\underline{a}, \underline{a}' \in \mathbb{R}^k$ , the 2 computations for  $H_0: \underline{a} \cdot \underline{\theta} = 0$  and  $H_0': \underline{a}' \cdot \underline{\theta} = 0$  are not independent, which implies that the 2 confidence coefficients are not both  $1-\alpha$ .

Remark: The test for the ANOVA null assumption  $H_0: \theta_1 = \theta_2 = \dots = \theta_k$  can be obtained by the hypothesis union-intersection

$$H_0 \Leftrightarrow \underline{\theta} \in \bigcap_{\underline{a} \in \mathcal{A}} \{ \underline{\xi} \in \mathbb{R}^k \mid \underline{a} \cdot \underline{\xi} = 0 \}$$

To obtain a criterion for this intersection corresponds to a maximization problem. See 11.2.4

An  $\alpha$ -level test for rejecting  $H_0$  is given by

$$\frac{\sum_{i=1}^k n_i (\bar{Y}_i - \bar{\bar{Y}})^2}{s^2} > (k-1) F_{k-1, N-k; \alpha} \text{ with } \bar{\bar{Y}} := \frac{1}{N} \sum_{i,j} Y_{ij}$$

↑ F distribution

from which one can obtain a  $(1-\alpha)$  confidence interval. Called ANOVA F-test



Consider a linear estimator for  $\beta$  of the form  $\sum_{i=1}^n d_i Y_i$  ← constants

It is unbiased if

$$E\left(\sum_{i=1}^n d_i Y_i\right) = \beta \Rightarrow \beta = \sum_{i=1}^n d_i (\alpha + \beta x_i) = \alpha \sum_{i=1}^n d_i + \beta \sum_{i=1}^n d_i x_i$$

is true for any  $\beta$ . Thus

$$\sum_{i=1}^n d_i = 0 \text{ and } \sum_{i=1}^n d_i x_i = 1$$

What about the best linear unbiased estimator (BLUE)?

The BLUE is the one with the smallest variance:

$$\text{Var}\left(\sum_{i=1}^n d_i Y_i\right) = \sum_{i=1}^n d_i^2 \text{Var}(Y_i) = \sigma^2 \sum_{i=1}^n d_i^2$$

$\Rightarrow$  We have to minimize  $\sum_{i=1}^n d_i^2$  "distance" from origin under the condition

$$\sum_{i=1}^n d_i = 0 \text{ and } \sum_{i=1}^n d_i x_i = 1 \text{ intersection of 2 "planes"}$$

The solution:  $d_i = \frac{(x_i - \bar{x})}{S_{xx}}$

$$\Rightarrow \text{Var}\left(\sum_{i=1}^n d_i Y_i\right) = \frac{1}{S_{xx}^2} \underbrace{\sum_{i=1}^n (x_i - \bar{x})^2}_{S_{xx}} \sigma^2 = \frac{\sigma^2}{S_{xx}}$$

Then we get (after an experiment)

$$b := \sum_{i=1}^n \frac{(x_i - \bar{x})}{S_{xx}} y_i = \sum_{i=1}^n \frac{(x_i - \bar{x})(y_i - \bar{y})}{S_{xx}} = \frac{S_{xy}}{S_{xx}}$$

$\sum (x_i - \bar{x}) \bar{y} = \bar{y} \sum (x_i - \bar{x}) = 0$

This coefficient is the one obtained by data fitting.

We can do the same for  $\alpha$  and one gets the BLUE for  $\alpha$  gives  $\alpha = \bar{y} - b\bar{x}$ .

If we do further analysis, we need to impose more on the distribution of  $\epsilon_i$ .

We consider the normal model:  $\epsilon_i \sim n(0, \sigma^2)$

In this context,  $Y_i \sim n(\alpha + \beta x_i, \sigma^2)$  ↑ imposed

Lemma: Assume  $Y_i \sim n(\alpha + \beta x_i, \sigma^2)$  then  $(\beta = \sum d_i Y_i \text{ for } \beta)$

the sample distribution for  $\hat{\alpha}$  and  $\hat{\beta}$  given by the BLUE are given by

$$\hat{\beta} \sim n\left(\beta, \frac{\sigma^2}{S_{xx}}\right) \text{ and } \hat{\alpha} \sim n\left(\alpha, \frac{\sigma^2}{n S_{xx}} \sum_{i=1}^n x_i^2\right)$$

The sample variance  $S^2$  given by

$$S^2 = \frac{1}{n-2} \sum_{i=1}^n (Y_i - \hat{\alpha} - \hat{\beta} x_i)^2 \text{ The factor } 1/(n-2) \text{ is imposed by the requirement that } S^2 \text{ is unbiased.}$$

satisfies  $\frac{n-2}{\sigma^2} S^2 \sim \chi_{n-2}^2$

In addition,  $S^2$  is independent of  $\hat{\alpha}$  and  $\hat{\beta}$ .

but  $\hat{\alpha}$  and  $\hat{\beta}$  are not independent. [Thm. 11.3.3]

Corollary:  $\frac{(\hat{\beta} - \beta) / \sqrt{\sigma^2 / S_{xx}}}{\sqrt{S^2 / \sigma^2}} = \frac{\hat{\beta} - \beta}{S / \sqrt{S_{xx}}} \sim t_{n-2}$  *student t dist.*  $\otimes$

$$\frac{(\hat{\alpha} - \alpha) \sqrt{\frac{\sigma^2}{n S_{xx}} \sum x_i^2}}{\sqrt{S^2 / \sigma^2}} = \frac{\hat{\alpha} - \alpha}{S \sqrt{\sum x_i^2 / n S_{xx}}} \sim t_{n-2}$$

From  $\otimes$  with the hypothesis  $H_0: \hat{\beta} = \beta$

we get the confidence interval with confident coef.  $(1-\alpha)$  as

$$\left[ \hat{\beta} - t_{n-2, \alpha/2} \frac{S}{\sqrt{S_{xx}}}, \hat{\beta} + t_{n-2, \alpha/2} \frac{S}{\sqrt{S_{xx}}} \right]$$

What about estimating  $Y$  for a given  $x_0$ ?

If we fix  $x_0$ , the point estimator for the corresponding  $Y$  is  $Y = \hat{\alpha} + \hat{\beta} x_0$ . One has

$$E(Y) = E(\hat{\alpha}) + x_0 E(\hat{\beta}) = \alpha + \beta x_0$$

$$\begin{aligned} \text{Var}(Y) &= \text{Var}(\hat{\alpha} + \hat{\beta} x_0) = \text{Var}(\hat{\alpha}) + x_0^2 \text{Var}(\hat{\beta}) + 2x_0 \text{Cov}(\hat{\alpha}, \hat{\beta}) \\ &= \dots = \sigma^2 \left( \frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}} \right) \end{aligned}$$

As a consequence

$$Y = \hat{\alpha} + \hat{\beta} x_0 \sim n \left( \alpha + \beta x_0, \sigma^2 \left( \frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}} \right) \right)$$

In order to estimate the parameter  $\sigma^2$  (which is usually unknown)

we use the sample variance  $S^2$ , which is independent of  $\hat{\alpha}$  and  $\hat{\beta}$ , and get

$$\frac{\hat{\alpha} + \hat{\beta} x_0 - (\alpha + \beta x_0)}{S \sqrt{\frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}}}} \sim t_{n-2}$$

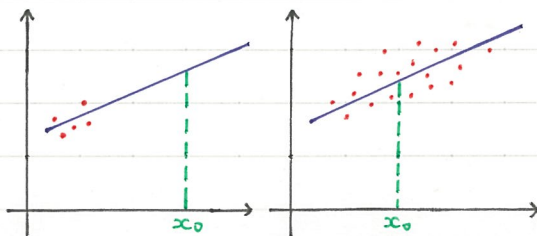
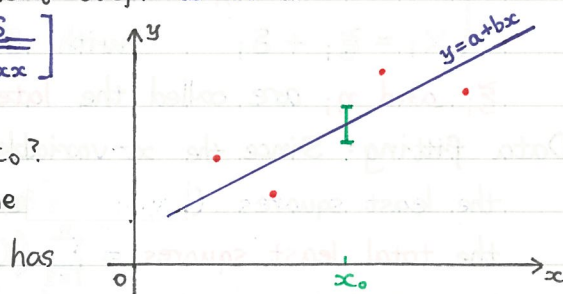
The related confidence interval with confident coef.  $1-\alpha$  is given by

$$\left[ \hat{\alpha} + \hat{\beta} x_0 - t_{n-2, \alpha/2} S \sqrt{\frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}}}, \hat{\alpha} + \hat{\beta} x_0 + t_{n-2, \alpha/2} S \sqrt{\frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}}} \right]$$

Remark: we have a smaller interval either by taking  $n$  large,

or by fixing  $x_1, \dots, x_n$  s.t.  $x_0 \cong \bar{x}$ .

We can also maximize  $S_{xx}$ .



## IX Regression models

### IX.1 Regression with errors in the variables

Idea: Before  $Y_i = \alpha + \beta x_i + \varepsilon_i$  with fixed  $x_i$ ;

Now  $X_i$  is to be a random variable.

Def. EIV model

$$\begin{cases} Y_i = \alpha + \beta \xi_i + \varepsilon_i & \text{with } \varepsilon_i \sim n(0, \sigma_\varepsilon^2) \\ X_i = \xi_i + \delta_i & \text{with } \delta_i \sim n(0, \sigma_\delta^2) \end{cases}$$

$\xi_i =: \eta_i$

$\xi_i$  and  $\eta_i$  are called the latent variables.

Data fitting: Since the  $x$ -variable has some errors

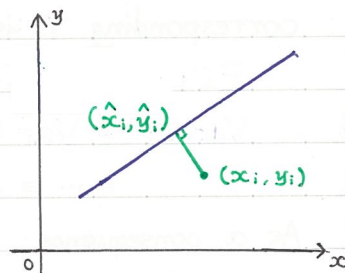
the least squares (based on vertical distance) is replaced by the total least squares =  $\sum_{i=1}^n ((x_i - \hat{x}_i)^2 + (y_i - \hat{y}_i)^2)$

(with the line given  $a+bx$ ) =  $\frac{1}{1+b^2} \sum_{i=1}^n ((y_i - (a+bx_i))^2)$

By minimization over  $a$  and  $b$ , one gets

$$a = \bar{y} - b\bar{x}$$

$$b = \frac{-(S_{xx} - S_{yy}) + \sqrt{(S_{xx} - S_{yy})^2 + 4S_{xy}^2}}{2S_{xy}}$$



Recall:  $Y_i \sim n(\alpha + \beta \xi_i, \sigma_\varepsilon^2)$ ;

$X_i \sim n(\xi_i, \sigma_\delta^2)$

This leads to the likelihood function for the sample  $\{(X_i, Y_i)\}_{i=1}^n$

$$\begin{aligned} L(\alpha, \beta, \xi_1, \dots, \xi_n, \sigma_\varepsilon^2, \sigma_\delta^2 | \underline{x}, \underline{y}) &= \\ &= \frac{1}{(2\pi)^n} \frac{1}{(\sigma_\varepsilon^2 \sigma_\delta^2)^{n/2}} \exp\left(-\sum \frac{(x_i - \xi_i)^2}{2\sigma_\delta^2}\right) \exp\left(-\sum_{i=1}^n \frac{(y_i - (\alpha + \beta \xi_i))^2}{2\sigma_\varepsilon^2}\right) \end{aligned}$$

Compute the MLE for the different parameters

In this general setting no local maximum.

One assumption:  $\sigma_{\xi}^2 = \lambda \sigma_{\epsilon}^2$  for a fixed  $\lambda \in \mathbb{R}$

With this assumption

$$L(\dots | \underline{x}, \underline{y}) = \frac{1}{(2\pi)^n} \frac{\lambda^{n/2}}{\sigma_{\xi}^{2n}} \left( \exp - \sum_i \frac{(x_i - \xi_i)^2 + \lambda(y_i - \alpha - \beta \xi_i)^2}{2\sigma_{\xi}^2} \right)$$

We are going to look at local maxima for this function,

as a function of the parameters (see Chapter IV on point estimators with MLE)

1) By taking derivatives with respect to  $\xi_i$ , and put the derivative equal to 0, one gets that a local maximum is observed for

$$\hat{\xi}_i = \frac{x_i + \lambda \beta (y_i - \alpha)}{1 + \lambda \beta^2}$$

By substituting these expressions in  $L$ , one finds

$$L(\alpha, \beta, \hat{\xi}_1, \dots, \hat{\xi}_n, \sigma_{\xi}^2 | \underline{x}, \underline{y}) = \frac{1}{(2\pi)^n} \frac{\lambda^{n/2}}{\sigma_{\xi}^{2n}} \exp\left(-\frac{\lambda}{2\sigma_{\xi}^2(1+\lambda\beta^2)} \sum_i (y_i - \alpha - \beta x_i)^2\right)$$

For computing the MLE for  $\alpha$  and  $\beta$  we set

$$y_i^* := \sqrt{\lambda} y_i; \quad \alpha^* := \sqrt{\lambda} \alpha; \quad \beta^* := \sqrt{\lambda} \beta \quad (\text{rescaling})$$

One gets

$$L(\alpha^*, \beta^*, \hat{\xi}_1, \dots, \hat{\xi}_n, \sigma_{\xi}^2 | \underline{x}, \underline{y}) = \frac{1}{(2\pi)^n} \frac{\lambda^{n/2}}{\sigma_{\xi}^{2n}} \exp\left(-\frac{1}{2\sigma_{\xi}^2(1+\lambda\beta^2)} \sum_i (y_i^* - \alpha^* - \beta^* x_i)^2\right)$$

(similar expression as at the beginning of the section for data fitting)

By the result for data fitting one gets

$$\begin{aligned} \hat{\alpha} &= \frac{\bar{y}^* - \beta^* \bar{x}}{\sqrt{\lambda}} = \bar{y} - \beta \bar{x} \\ \hat{\beta} &= \frac{\beta^*}{\sqrt{\lambda}} = \frac{-(S_{xx} - S_{y^*y^*}) + \sqrt{(S_{xx} - S_{y^*y^*})^2 + 4S_{xy^*}}}{2S_{xy^*}} \\ &= \frac{-(S_{xx} - \lambda S_{yy}) + \sqrt{(S_{xx} - \lambda S_{yy})^2 + 4\lambda S_{xy}^2}}{2\lambda S_{xy}} \end{aligned}$$

Remark:

For  $\lambda = 1$ , we get the result of the data fitting

(obtained with the total least square)

This can be considered as a justification of the total least square.

Remark: From

$$L(\hat{\alpha}, \hat{\beta}, \hat{\xi}_1, \dots, \hat{\xi}_n, \sigma_s^2 | \underline{x}, \underline{y}) = \frac{1}{(2\pi)^{n/2}} \frac{\lambda^{n/2}}{\sigma_s^{2n}} \exp\left(-\frac{\lambda}{2\sigma_s^2(1+\lambda\hat{\beta}^2)} \sum_i (y_i - \hat{\alpha} - \hat{\beta}x_i)^2\right)$$

We can differentiate it with respect to  $\sigma_s^2$ , and find the critical point.

One gets

$$\hat{\sigma}_s^2 \stackrel{\text{MLE}}{\text{for } \sigma_s^2} = \frac{1}{n} \frac{\lambda}{2(1+\lambda\hat{\beta}^2)} \sum_i (y_i - \hat{\alpha} - \hat{\beta}x_i)^2$$

What about confidence interval for  $\beta$ ?  $\rightsquigarrow$  very complicated

One way to get an approximate solution: Consider

$$\hat{\sigma}_\beta^2 := \frac{(1+\lambda\hat{\beta}^2)(S_{xx}S_{yy} - S_{xy}^2)}{(S_{xx} - \lambda S_{yy})^2 + 4\lambda S_{xy}^2}$$

is a consistent estimator for  $\sigma_\beta^2$

in precise sense  
see Chap VII

Chap VII  $\rightarrow$  when sample size  $\rightarrow \infty$ ,  $\hat{\sigma}_\beta^2 \rightarrow \sigma_\beta^2$

Then by the central limit thm, one has

$$\text{we don't know it} \rightarrow \frac{\hat{\beta} - \beta}{\sigma_\beta / \sqrt{n}} \xrightarrow{n \rightarrow \infty} \mathcal{N}(0, 1)$$

from which one obtains the approximate  $(1-\alpha)$  confidence interval

$$\left[ \hat{\beta} - z_{\alpha/2} \frac{\hat{\sigma}_\beta}{\sqrt{n}}, \hat{\beta} + z_{\alpha/2} \frac{\hat{\sigma}_\beta}{\sqrt{n}} \right]$$

⚠ It is not a  $(1-\alpha)$  confidence interval,

but for  $n$  large, it converges to a  $(1-\alpha)$  confidence interval.

## IX.2 Logistic regression (0,1 model)

$$E(Y_i) = \pi_i = P(Y_i = 1)$$

Model:  $\{Y_i\}$  independent variables with  $Y_i \sim \text{Bernoulli}(\pi_i)$  with

$$\pi_i = \frac{e^{\alpha + \beta x_i}}{1 + e^{\alpha + \beta x_i}} \in [0, 1] \Leftrightarrow \ln \frac{\pi_i}{1 - \pi_i} = \alpha + \beta x_i$$

$\underbrace{\hspace{10em}}_{\text{prob of success / prob of failure}} =: \text{odds}$

Remark: We cannot draw a graph  $(x_i, y_i)$  and use the least squares

but we can use the MLE.

One has  $L(\alpha, \beta | \underline{x}, \underline{y}) = \prod_i \pi(x_i)^{y_i} (1 - \pi(x_i))^{1 - y_i}$  under the assumption of independence of measurements

with  $\pi_i = \pi(x_i)$

pmf for Bernoulli

and  $\pi$  the function  $x \mapsto \pi(x) := \frac{e^{\alpha + \beta x}}{1 + e^{\alpha + \beta x}}$

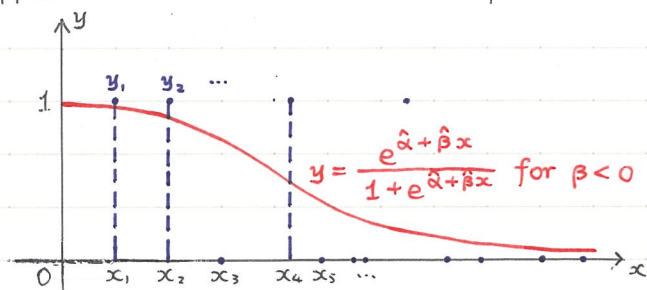
We can then compute

$$\frac{\partial}{\partial \alpha} L(\alpha, \beta | \underline{x}, \underline{y}) = 0 \quad \text{and} \quad \frac{\partial}{\partial \beta} L(\alpha, \beta | \underline{x}, \underline{y}) = 0$$

and solve the system.



We can not solve this system explicitly, but a computer can do it easily. Suppose we have obtained  $\hat{\alpha}$  and  $\hat{\beta}$  numerically, then we can plot the result



Remember  $E(Y) = \pi(x)$

We can get some confidence intervals.

If we want to consider several measures for a given  $x$ , one has to use a binomial distribution.

More precisely, if  $n_i$  independent, Bernoulli observations are measured at  $x_i$ , then Bernoulli  $(\pi_i)$  has to be replaced by binomial  $(n_i, \pi_i)$ .

Then  $L(\alpha, \beta | \underline{x}, \underline{y}) = \prod_i \binom{n_i}{y_i} \pi(x_i)^{y_i} (1 - \pi(x_i))^{n_i - y_i}$   $\hookrightarrow \pi = \pi(x_i)$

with  $y_i$  the number of success at  $x_i$ ,

and we can compute the MLE for  $\alpha$  and for  $\beta$  (with a computer)

Application: see (3.2) of Appendix 13

### Conclusion for the course

We have only touched the surface of statistics, but we have opened many doors, and you can continue in these directions.