

Global existence of solutions of the
Navier-Stokes equations with the Coriolis force

Graduate School of Mathematics, Nagoya University
521301017 Hiroki Ito

January 18, 2016

Abstract

The Cauchy problem for the Navier-Stokes equations with the Coriolis force is considered. It is proved that a similar a priori estimate, which is derived for the Navier-Stokes equations by Lei-Lin [12], holds under the effect of the Coriolis force. As an application existence of a unique global solution for arbitrary speed of rotation is proved, as well as its asymptotic behavior.

Contents

| | | |
|----------|---|-----------|
| 1 | Introduction | 3 |
| 2 | H^s Theory | 6 |
| 2.1 | A Priori Estimate and Its Application to H^s Theory | 6 |
| 2.2 | Proof of Theorem 2.3 | 9 |
| 2.3 | Proof of Theorem 2.5 | 11 |
| 2.4 | Proof of Theorem 2.7 | 12 |
| 3 | χ^{-1} Theory | 15 |
| 3.1 | Main Theorem in χ^{-1} Theory | 15 |
| 3.2 | Existence of Solutions for Any Time Interval | 17 |
| 3.3 | Existence of Local Solutions for Any Initial Data | 21 |
| 3.4 | Proof of Theorem 3.1 | 27 |

Chapter 1

Introduction

In this thesis, we consider the initial value problem of the Navier-Stokes equations with the Coriolis force in \mathbb{R}^3 ,

$$\begin{cases} \partial_t u - \nu \Delta u + \Omega e_3 \times u + (u, \nabla)u + \nabla p = 0, & \text{in } (0, \infty) \times \mathbb{R}^3, \\ \operatorname{div} u = 0, & \text{in } (0, \infty) \times \mathbb{R}^3, \\ u|_{t=0} = u_0, & \text{in } \mathbb{R}^3, \end{cases} \quad (\text{NS}_\Omega)$$

where $u = u(t, x) = (u_1(t, x), u_2(t, x), u_3(t, x))$ denotes the unknown velocity field, and $p = p(t, x)$ denotes the unknown scalar pressure, while $u_0 = u_0(x) = (u_0^1(x), u_0^2(x), u_0^3(x))$ denotes the initial velocity field. The constant $\nu > 0$ denotes the viscosity coefficient of the fluid, and $\Omega \in \mathbb{R}$ represents the speed of rotation around the vertical unit vector $e_3 = (0, 0, 1)$, which is called the Coriolis parameter.

Recently, this problem gained some attention due to its importance in applications to geophysical flows, see e.g. [4]. Mathematically, (NS_Ω) also have a interesting feature that there exists a global solution for arbitrary large data provided the speed of rotation Ω is large enough, see e.g. [1, 4, 9]. There are another type of results which shows the existence of a global solution uniformly in Ω provided the data is sufficiently small, see e.g. [5, 8, 11, 10]. The purpose of this thesis is, concerning to the latter, to relax the smallness condition of the data, based on the idea for the Navier-Stokes equations, $\Omega = 0$ in (NS_Ω) , by [12].

Before stating our main results, we give a definition of function spaces. For $m \in \mathbb{R}$, we define

$$\chi^m(\mathbb{R}^3) := \{f \in \mathcal{S}' \mid \widehat{f} \in L^1_{\text{loc}}, \|f\|_{\chi^m} := \int_{\mathbb{R}^3} |\xi|^m |\widehat{f}(\xi)| d\xi < \infty\}.$$

Recently, Lei and Lin introduced the space χ^{-1} , which is contained in BMO^{-1} and equivalent to the Fourier-Herz space $\dot{\mathcal{B}}_1^{-1}$. It is known that $H^s(\mathbb{R}^3) \subseteq \chi^{-1}$, if $s > \frac{1}{2}$, see Lemma 2.1. Moreover it is known that there is an example so that $H^{\frac{1}{2}}(\mathbb{R}^3) \not\subseteq \chi^{-1}$, see [12]. It is also known that $\chi^{-1} \not\subseteq H^{\frac{1}{2}}(\mathbb{R}^3)$, see [14].

Theorem 2.3. Let $u_0 \in \chi^{-1}$ satisfy $\operatorname{div} u_0 = 0$ and $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$. For $T > 0$, assume that $u \in C([0, T]; \chi^{-1})$ is a solution to (NS_Ω) in the distribution sense satisfying

$$u \in L^1(0, T; \chi^1), \quad \partial_t u \in L^1(0, T; \chi^{-1}).$$

Then, u satisfies

$$\|u(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3} \|u_0\|_{\chi^{-1}}) \int_0^t \|u(\tau)\|_{\chi^1} d\tau \leq \|u_0\|_{\chi^{-1}}, \quad 0 \leq t < T. \quad (1.0.1)$$

Remark 1.1. (1) This a priori estimate is first derived in the case $\Omega = 0$ in [12, Proof of Theorem 1.1]. Here, Theorem 2.3 states that the same estimate also holds under the effect of the Coriolis force.

(2) In this thesis, we define the Fourier transform of f by

$$\widehat{f}(\xi) = \mathcal{F}[f](\xi) := \int e^{-ix \cdot \xi} f(x) dx.$$

The constant $(2\pi)^3$ in the theorem appears from the following formula:

$$\mathcal{F}[fg](\xi) = (2\pi)^{-3} (\widehat{f} * \widehat{g})(\xi),$$

where $f * g$ denotes the convolution of f and g .

As an application of Theorem 2.3 we obtain the global solution to (NS_Ω) .

Theorem 2.5. Let $s > 3/2$ and $\Omega \in \mathbb{R}$. Assume that $u_0 \in H^s(\mathbb{R}^3)$ satisfy $\operatorname{div} u_0 = 0$ and $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$. Then, there exists a unique global solution $u \in C([0, \infty); H^s(\mathbb{R}^3))$ to (NS_Ω) satisfying

$$u \in AC([0, \infty); H^{s-1}(\mathbb{R}^3)) \cap L_{\text{loc}}^1(0, \infty; H^{s+1}(\mathbb{R}^3))$$

and

$$\sup_{t>0} \{ \|u(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3} \|u_0\|_{\chi^{-1}}) \int_0^t \|u(\tau)\|_{\chi^1} d\tau \} \leq \|u_0\|_{\chi^{-1}}.$$

Remark 1.2. Since $s > 3/2$, we have $H^s \hookrightarrow \chi^{-1}$ by Lemma 2.1. For a interval I and a Banach space X , $AC(I; X)$ denotes the space of X -valued absolutely continuous functions. There are several results which treats the existence of a unique global solution to (NS_Ω) , see [10] and reference therein. The advantage of this result is that the condition of the size of the data is merely $\|u_0\|_{\chi^{-1}} < (2\pi)^3\nu$.

In chapter 3, we show the existence of a unique global solution for the data $u_0 \in \chi^{-1}$ with $\|u_0\|_{\chi^{-1}} < (2\pi)^3\nu$. For the Navier-Stokes case $\Omega = 0$, see [14, Theorem 1.3].

Theorem 3.1. Let $u_0 \in \chi^{-1}$ and $\|u_0\|_{\chi^{-1}} < (2\pi)^3\nu$. Then, there is a unique global in time solution $u \in C([0, \infty); \chi^{-1})$ of (NS_Ω) satisfying

$$u \in L^2(0, \infty; \chi^0) \cap L^1(0, \infty; \chi^1), \quad \partial_t u \in L^1(0, \infty; \chi^{-1}),$$

and

$$\sup_{t>0} \left\{ \|u(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3}\|u_0\|_{\chi^{-1}}) \int_0^t \|u(\tau)\|_{\chi^1} d\tau \right\} \leq \|u_0\|_{\chi^{-1}}.$$

Remark 1.3. (1) There are several results which treats the existence of a unique global solution to (NS_Ω) , see [10] and reference therein. In particular, the spaces FM_0^{-1} , which is considered by Giga, Inui, Mahalov, and Saal [5], and $\mathcal{B}_{1,2}^{-1}$ by [10], are larger than χ^{-1} . However, the advantage of this result is that the condition of the size of the data is merely $\|u_0\|_{\chi^{-1}} < (2\pi)^3\nu$.

(2) In the Navier-Stokes equations, the case $\Omega = 0$, the corresponding result is proved in [12, Theorem 1.1]. We notice that there is also the another approach by [14, Theorem 1.3].

Chapter 2

H^s Theory

2.1 A Priori Estimate and Its Application to H^s Theory

In this thesis, we only use spaces χ^{-1} , χ^0 , and χ^1 below, so we summarize elementary estimates concerning the spaces we will use later.

Lemma 2.1. (1) For $m > -3/2$, and $s > m + 3/2$,

$$\|f\|_{\chi^m(\mathbb{R}^3)} \leq C \|f\|_{L^2}^{1-\frac{1}{s}(m+\frac{3}{2})} \|f\|_{\dot{H}^s}^{\frac{1}{s}(m+\frac{3}{2})}.$$

$$(2) \|f\|_{\chi^0} \leq \|f\|_{\chi^{-1}}^{1/2} \|f\|_{\chi^1}^{1/2}.$$

$$(3) \|\nabla f\|_{L^\infty} \leq (2\pi)^{-3} \|f\|_{\chi^1}.$$

Remark 2.2. Taking $m = -1, 1$ in Lemma 2.1 (1) respectively, we have for $s > 1/2$,

$$\|f\|_{\chi^{-1}(\mathbb{R}^3)} \leq C \|f\|_{L^2}^{1-\frac{1}{2s}} \|f\|_{\dot{H}^s}^{\frac{1}{2s}},$$

and for $s > 5/2$,

$$\|f\|_{\chi^1(\mathbb{R}^3)} \leq C \|f\|_{L^2}^{1-\frac{5}{2s}} \|f\|_{\dot{H}^s}^{\frac{5}{2s}}.$$

proof. (1) We take $R > 0$, which is determined later, to divide the integral

$$\begin{aligned} \|f\|_{\chi^m} &= \int_{|\xi| \leq R} |\xi|^m |\widehat{f}(\xi)| d\xi + \int_{|\xi| > R} |\xi|^m |\widehat{f}(\xi)| d\xi \\ &\leq \left(\int_{|\xi| \leq R} |\xi|^{2m} d\xi \right)^{1/2} (2\pi)^{\frac{3}{2}} \|f\|_{L^2} + \left(\int_{|\xi| > R} |\xi|^{2(m-s)} d\xi \right)^{1/2} \|f\|_{\dot{H}^s} \\ &= |S^2|^{1/2} \left(\frac{1}{\sqrt{2m+3}} R^{m+3/2} (2\pi)^{\frac{3}{2}} \|f\|_{L^2} + \frac{1}{\sqrt{2(s-m)-3}} R^{m-s+3/2} \|f\|_{\dot{H}^s} \right). \end{aligned}$$

Then, choosing $R = \|f\|_{L^2}^{-1/s} \|f\|_{\dot{H}^2}^{1/s}$, we obtain the desired result.

(2) This estimate is easily derived by the Hölder inequality,

$$\|f\|_{\chi^0} = \int |\xi|^{-1/2} |\widehat{f}(\xi)|^{1/2} |\xi|^{1/2} |\widehat{f}(\xi)|^{1/2} d\xi \leq \|f\|_{\chi^{-1}}^{1/2} \|f\|_{\chi^1}^{1/2}.$$

(3) This is also easily derived from the Fourier inversion formula and the Hausdorff-Young inequality. \square

Now we state our main results.

Theorem 2.3. *Let $u_0 \in \chi^{-1}$ satisfy $\operatorname{div} u_0 = 0$ and $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$. For $T > 0$, assume that $u \in C([0, T]; \chi^{-1})$ is a solution to (NS_Ω) in the distribution sense satisfying*

$$u \in L^1(0, T; \chi^1), \quad \partial_t u \in L^1(0, T; \chi^{-1}).$$

Then, u satisfies

$$\|u(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3} \|u_0\|_{\chi^{-1}}) \int_0^t \|u(\tau)\|_{\chi^1} d\tau \leq \|u_0\|_{\chi^{-1}}, \quad 0 \leq t < T. \quad (2.1.1)$$

Remark 2.4. From the a priori estimate (2.1.1), we especially obtain

$$\|u\|_{L^\infty(0, T; \chi^{-1})} \leq \|u_0\|_{\chi^{-1}}, \quad \|u\|_{L^1(0, T; \chi^1)} \leq \frac{\|u_0\|_{\chi^{-1}}}{\nu - (2\pi)^{-3} \|u_0\|_{\chi^{-1}}}.$$

As an application of Theorem 2.3 we obtain the global solution to (NS_Ω) .

Theorem 2.5. *Let $s > 3/2$ and $\Omega \in \mathbb{R}$. Assume that $u_0 \in H^s(\mathbb{R}^3)$ satisfy $\operatorname{div} u_0 = 0$ and $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$. Then, there exists a unique global solution $u \in C([0, \infty); H^s(\mathbb{R}^3))$ to (NS_Ω) satisfying*

$$u \in AC([0, \infty); H^{s-1}(\mathbb{R}^3)) \cap L^1(0, \infty; H^{s+1}(\mathbb{R}^3))$$

and

$$\sup_{t>0} \left\{ \|u(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3} \|u_0\|_{\chi^{-1}}) \int_0^t \|u(\tau)\|_{\chi^1} d\tau \right\} \leq \|u_0\|_{\chi^{-1}}.$$

Remark 2.6. Since $s > 3/2$, we have $H^s \hookrightarrow \chi^{-1}$ by Lemma 2.1. For a interval I and a Banach space X , $AC(I; X)$ denotes the space of X -valued absolutely continuous functions. There are several results which treats the existence of a unique global solution to (NS_Ω) , see [10] and reference therein. The advantage of this result is that the condition of the size of the data is merely $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$.

Next theorem states the asymptotic behavior of a given global solution to (NS_Ω) .

Theorem 2.7. *Let $s > 1/2$ and $\Omega \in \mathbb{R}$. Assume that $u \in C([0, \infty); H^s(\mathbb{R}^3))$ is a global solution to (NS_Ω) satisfying*

$$u \in AC([0, \infty); H^{s-1}(\mathbb{R}^3)) \cap L^1_{\text{loc}}([0, \infty); H^{s+1}(\mathbb{R}^3)).$$

Then, $\lim_{t \rightarrow \infty} \|u(t)\|_{\chi^{-1}} = 0$.

Remark 2.8. In the Navier-Stokes case $\Omega = 0$, this result corresponds to the result in [3]. In that result, the assumption is only $u \in C([0, \infty); \chi^{-1})$ is a global solution. Compared with that result, additional assumptions are imposed for the uniqueness of solutions.

As an application of Theorem 2.7 we obtain the following.

Corollary 2.9. *The global solution to (NS_Ω) derived in Theorem 2.5 satisfies*

$$\lim_{t \rightarrow \infty} \|u(t)\|_{\chi^{-1}} = 0.$$

This chapter is organized as follows. In Section 2.2 we give a proof of Theorem 2.3. In Section 2.3 we prove Theorem 2.5 as an application of Theorem 2.3. In Section 2.4 we give a proof of Theorem 2.7.

2.2 Proof of Theorem 2.3

In this section we give a proof of Theorem 2.3.

Proof of Theorem 2.3. By applying the Fourier transform to the equation, we have

$$\partial_t \widehat{u} + \nu |\xi|^2 \widehat{u} + \Omega e_3 \times \widehat{u} + \mathcal{F}[(u, \nabla)u] + i\xi \widehat{p} = 0.$$

Thus, we obtain

$$\begin{aligned} \partial_t |\widehat{u}|^2 &= 2\operatorname{Re}(\partial_t \widehat{u} \cdot \overline{\widehat{u}}) \\ &= -2\nu |\xi|^2 |\widehat{u}|^2 - 2\Omega \operatorname{Re}[(e_3 \times \widehat{u}) \cdot \overline{\widehat{u}}] - 2\operatorname{Re}\{\mathcal{F}[(u, \nabla)u] \cdot \overline{\widehat{u}}\} - 2\operatorname{Re}[(i\xi \widehat{p}) \cdot \overline{\widehat{u}}]. \end{aligned}$$

Here, since

$$(e_3 \times \widehat{u}) \cdot \overline{\widehat{u}} = -\widehat{u}_2 \overline{\widehat{u}_1} + \widehat{u}_1 \overline{\widehat{u}_2} = 2i \operatorname{Im}[\widehat{u}_1 \overline{\widehat{u}_2}],$$

we observe that $\operatorname{Re}[(e_3 \times \widehat{u}) \cdot \overline{\widehat{u}}] = 0$. Also, we have $(i\xi \widehat{p}) \cdot \overline{\widehat{u}} = 0$, since $\operatorname{div} u = 0$. Moreover, we notice that

$$\begin{aligned} \mathcal{F}[(u, \nabla)u]_j(\xi) &= \sum_{k=1}^3 (2\pi)^{-3} \widehat{u}_k * \widehat{\partial_k u_j}(\xi) \\ &= \sum_{k=1}^3 (2\pi)^{-3} \int \widehat{u}_k(\xi - \eta) i\eta_k \widehat{u}_j(\eta) d\eta \\ &= \sum_{k=1}^3 (2\pi)^{-3} i\xi_k \int \widehat{u}_k(\xi - \eta) \widehat{u}_j(\eta) d\eta, \end{aligned}$$

since $\sum_{k=1}^3 (\xi_k - \eta_k) \widehat{u}_k(\xi - \eta) = 0$. Therefore, we obtain

$$\begin{aligned} \partial_t |\widehat{u}|^2 + 2\nu |\xi|^2 |\widehat{u}|^2 &\leq 2(2\pi)^{-3} \sum_{j,k=1}^3 |\xi_k| (|\widehat{u}_k| * |\widehat{u}_j|) |u_j| \\ &\leq 2(2\pi)^{-3} |\xi| |\widehat{u}| (|\widehat{u}| * |\widehat{u}|). \end{aligned}$$

Then, for $\varepsilon > 0$, we observe that

$$\begin{aligned} \partial_t (|\widehat{u}|^2 + \varepsilon)^{1/2} &= \frac{\partial_t |\widehat{u}|^2}{2(|\widehat{u}|^2 + \varepsilon)^{1/2}} \\ &\leq -\frac{\nu |\xi|^2 |\widehat{u}|^2}{(|\widehat{u}|^2 + \varepsilon)^{1/2}} + (2\pi)^{-3} \frac{|\xi| |\widehat{u}|}{(|\widehat{u}|^2 + \varepsilon)^{1/2}} (|\widehat{u}| * |\widehat{u}|). \end{aligned}$$

Integrating with respect to t , we obtain

$$\begin{aligned} & (|\widehat{u}(t, \xi)|^2 + \varepsilon)^{1/2} + \int_0^t \frac{\nu |\xi|^2 |\widehat{u}(\tau, \xi)|^2}{(|\widehat{u}(\tau, \xi)|^2 + \varepsilon)^{1/2}} d\tau \\ & \leq (|\widehat{u}_0(\xi)|^2 + \varepsilon)^{1/2} + (2\pi)^{-3} \int_0^t \frac{|\xi| |\widehat{u}(\tau, \xi)|}{(|\widehat{u}(\tau, \xi)|^2 + \varepsilon)^{1/2}} (|\widehat{u}(\tau)| * |\widehat{u}(\tau)|)(\xi) d\tau. \end{aligned}$$

Then, letting $\varepsilon \rightarrow 0$, we get

$$|\widehat{u}(t, \xi)| + \int_0^t \nu |\xi|^2 |\widehat{u}(\tau, \xi)| d\tau \leq |\widehat{u}_0(\xi)| + (2\pi)^{-3} \int_0^t |\xi| (|\widehat{u}(\tau)| * |\widehat{u}(\tau)|)(\xi) d\tau.$$

Finally, dividing by $|\xi|$, and then integrating over \mathbb{R}^n , we obtain

$$\|u(t)\|_{\chi^{-1}} + \nu \int_0^t \|u(\tau)\|_{\chi^1} d\tau \leq \|u_0\|_{\chi^{-1}} + (2\pi)^{-3} \int_0^t \|u(\tau)\|_{\chi^0}^2 d\tau.$$

By applying Lemma 2.1 (2), we obtain,

$$\|u(t)\|_{\chi^{-1}} + \nu \|u\|_{L^1((0,t); \chi^1)} \leq \|u_0\|_{\chi^{-1}} + (2\pi)^{-3} \|u\|_{L^\infty((0,t); \chi^{-1})} \|u\|_{L^1((0,t); \chi^1)}. \quad (2.2.1)$$

To derive the desired estimate (2.1.1), it suffices to prove that

$$\|u\|_{L^\infty((0,t); \chi^{-1})} \leq \|u_0\|_{\chi^{-1}}, \quad 0 \leq t < T.$$

For the proof, we first show that

$$\|u(t)\|_{\chi^{-1}} < (2\pi)^3 \nu, \quad 0 \leq t < T \quad (2.2.2)$$

holds by contradiction. From the assumption $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$ and $u \in C([0, T]; \chi^{-1})$, we observe that there exists $\delta > 0$ such that (2.2.2) holds on $[0, \delta)$. Now assume that there exists $t_0 \in (0, T)$ such that $\|u(t)\|_{\chi^{-1}} < (2\pi)^3 \nu$ for $0 < t < t_0$ and

$$\|u(t_0)\|_{\chi^{-1}} = (2\pi)^3 \nu,$$

then by (2.2.1) we reach the contradiction

$$(2\pi)^3 \nu = \|u(t_0)\|_{\chi^{-1}} \leq \|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu,$$

since $\|u\|_{L^\infty((0,t_0); \chi^{-1})} = (2\pi)^3 \nu$. Therefore, we obtain (2.2.2). Finally, applying (2.2.2) to estimate on the right hand side of (2.2.1), we obtain

$$\|u(t)\|_{\chi^{-1}} < \|u_0\|_{\chi^{-1}}, \quad 0 \leq t < T.$$

This completes the proof. \square

2.3 Proof of Theorem 2.5

Below we fix $\Omega \in \mathbb{R}$. For the existence of local solutions, we employ the following result.

Proposition 2.10. *Let $s > 3/2$. For $u_0 \in H^s(\mathbb{R}^3)$ with $\operatorname{div} u_0 = 0$, there exists $T = T(|\Omega|, s, \|u_0\|_{H^s}) > 0$ such that (NS_Ω) admits a unique strong solution $u \in C([0, T]; H^s(\mathbb{R}^3))$ satisfying*

$$u \in AC([0, T]; H^{s-1}(\mathbb{R}^3)) \cap L^1(0, T; H^{s+1}(\mathbb{R}^3)).$$

Remark 2.11. (1) For the proof, we refer to [13, Lemma 3.1]. We notice that the condition in [13, Lemma 3.1] is $s > 3/2 + 1$, because their main subject is the Euler equation. For the above statement, $s > 3/2$ is sufficient.

(2) In this proposition, the size of T is characterized by

$$C_0|\Omega|T + C_1\|u_0\|_{H^s}(T + T^{1/2}\nu^{-1/2}) \leq \frac{1}{2}. \quad (2.3.1)$$

(3) Since $s > 3/2$, the solution constructed by Proposition 2.10 satisfies the assumptions in Theorem 2.3. In particular, since

$$\partial_t u = \nu \Delta u - \Omega \mathbb{P}(e_3 \times u) - \mathbb{P}(u, \nabla u) \quad \text{in } H^{s-1}$$

holds for a.e. $t \in (0, T)$, where $\mathbb{P} = (\delta_{ij} + R_i R_j)_{i,j}$ is the Helmholtz projection, we easily observe that $\partial_t u \in L^1(0, T; \chi^{-1})$.

We will use the following energy estimate.

Proposition 2.12. *Let $s \geq 0$ and $T > 0$. Assume that $u \in C([0, T]; H^s(\mathbb{R}^3))$ is a solution to (NS_Ω) satisfying*

$$u \in AC([0, T]; H^{s-1}(\mathbb{R}^3)) \cap L^1(0, T; H^{s+1}(\mathbb{R}^3)).$$

Then, u satisfies

$$\|u(t)\|_{H^s} \leq \|u_0\|_{H^s} e^{C \int_0^t \|\nabla u(\tau)\|_{L^\infty} d\tau}, \quad 0 \leq t < T.$$

Remark 2.13. For the proof of this proposition, we also refer to [13, Proof of Theorem 4.1]. There, we easily observe that

$$\frac{d}{dt} \|u(t)\|_{H^s} \leq C \|\nabla u(t)\|_{L^\infty} \|u(t)\|_{H^s}$$

holds for $s \geq 0$. We notice that the term concerning $\Omega e_3 \times u$ vanishes due to its property of the skew symmetry in H^s .

Now we are in a position to prove Theorem 2.5.

Proof of Theorem 2.5. Let T^* be the maximal existence time of a unique solution derived by applying Proposition 2.10 repeatedly. Now assume $T^* < \infty$. Then, by (2.3.1), we must have

$$\lim_{t \rightarrow T^*} \|u(t)\|_{H^s} = \infty. \quad (2.3.2)$$

Since this solution satisfies the energy estimate in Proposition 2.12, we have

$$\|u(t)\|_{H^s} \leq \|u_0\|_{H^s} e^{C \int_0^t \|\nabla u(\tau)\|_{L^\infty} d\tau}, \quad 0 \leq t < T^*.$$

Then, since $\|u_0\|_{\chi^{-1}} < (2\pi)^3 \nu$, applying Theorem 2.3 we obtain

$$\int_0^{T^*} \|\nabla u(\tau)\|_{L^\infty} d\tau \leq \|u\|_{L^1(0, T^*; \chi^1)} \leq \frac{\|u_0\|_{\chi^{-1}}}{\nu - (2\pi)^{-3} \|u_0\|_{\chi^{-1}}}.$$

This implies $\sup_{0 < t < T^*} \|u(t)\|_{H^s} < \infty$, which contradicts to (2.3.2). \square

2.4 Proof of Theorem 2.7

In this section we give a proof of Theorem 2.7.

We take $\varepsilon > 0$ arbitrary small. Since $u_0 \in H^s \hookrightarrow \chi^{-1}$, we are able to take $R_0 > 0$ such that

$$\int_{|\xi| > R_0} |\xi|^{-1} |\widehat{u}_0(\xi)| d\xi < \frac{\varepsilon}{2}.$$

Now we set

$$v_0 = \mathcal{F}^{-1}[\chi_{\{|\xi| \leq R_0\}} \widehat{u}_0], \quad w_0 = \mathcal{F}^{-1}[\chi_{\{|\xi| > R_0\}} \widehat{u}_0].$$

Then, we observe that $v_0 \in H^\infty$, $w_0 \in H^s$, $u_0 = v_0 + w_0$, and

$$\|w_0\|_{\chi^{-1}} < \frac{\varepsilon}{2}.$$

By applying Theorem 2.5 for the initial data w_0 we obtain the solution (w, p_w) to (NS $_\Omega$). Then, $w \in C([0, \infty); H^s) \cap L^1(0, \infty; H^{s+1})$ satisfies

$$\|w(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3} \|w_0\|_{\chi^{-1}}) \int_0^t \|w(\tau)\|_{\chi^1} d\tau \leq \|w_0\|_{\chi^{-1}} < \frac{\varepsilon}{2}, \quad t > 0. \quad (2.4.1)$$

Now we set $v := u - w$. Then, $v \in C([0, \infty); H^s)$ satisfies

$$v \in AC([0, \infty); H^{s-1}(\mathbb{R}^3)) \cap L^1(0, \infty; H^{s+1}(\mathbb{R}^3))$$

and

$$\begin{cases} \partial_t v + \nu \Delta v + \Omega e_3 \times v + (v, \nabla)v + (w, \nabla)v + (v, \nabla)w + \nabla(p - p_w) = 0, \\ \operatorname{div} v = 0, \\ v|_{t=0} = v_0. \end{cases}$$

Taking L^2 -inner product with v , the equation becomes

$$\frac{d}{dt} \|v(t)\|_{L^2}^2 + \nu \|\nabla v(t)\|_{L^2}^2 = \langle (v, \nabla)w, v \rangle_{L^2}.$$

Since

$$\langle (v, \nabla)w, v \rangle_{L^2} = -\langle w, (v, \nabla)v \rangle_{L^2},$$

we obtain

$$\begin{aligned} |\langle (v, \nabla)w, v \rangle_{L^2}| &\leq \|w\|_{L^\infty} \|v\|_{L^2} \|\nabla v\|_{L^2} \\ &\leq C \|w\|_{\chi^0} \|v\|_{L^2} \|\nabla v\|_{L^2} \\ &\leq C_\nu \|w\|_{\chi^0}^2 \|v\|_{L^2}^2 + \frac{\nu}{2} \|\nabla v\|_{L^2}^2 \end{aligned}$$

Therefore, we obtain

$$\frac{d}{dt} \|v(t)\|_{L^2}^2 + \frac{\nu}{2} \|\nabla v(t)\|_{L^2}^2 = C_\nu \|w(t)\|_{\chi^0}^2 \|v(t)\|_{L^2}^2.$$

Then, by Gronwall's inequality,

$$\|v(t)\|_{L^2}^2 + \frac{\nu}{2} \int_0^t \|\nabla v(\tau)\|_{L^2}^2 d\tau \leq \|v(0)\|_{L^2}^2 e^{C_\nu \int_0^t \|w(\tau)\|_{\chi^0}^2 d\tau}. \quad (2.4.2)$$

Here, by (2.4.1) we have

$$\int_0^t \|w(\tau)\|_{\chi^0}^2 d\tau \leq \|w\|_{L^\infty((0,t); \chi^{-1})} \|w\|_{L^1((0,t); \chi^1)} \leq \frac{\|w_0\|_{\chi^{-1}}^2}{\nu - (2\pi)^{-3} \|w_0\|_{\chi^{-1}}}. \quad (2.4.3)$$

Therefore, by Lemma 2.1 (1), (2.4.2), (2.4.3) we obtain

$$\int_0^\infty \|v(t)\|_{\chi^{-1}}^4 d\tau \leq \int_0^\infty \|v(t)\|_{L^2}^2 \|\nabla v(t)\|_{L^2}^2 d\tau \leq \frac{2}{\nu} \|v_0\|_{L^2}^4 \exp\left(\frac{C_\nu \|w_0\|_{\chi^{-1}}^2}{\nu - (2\pi)^{-3} \|w_0\|_{\chi^{-1}}}\right).$$

Since $v \in C([0, \infty); \chi^{-1})$, we observe that there exists $t_0 > 0$ such that $\|v(t_0)\|_{\chi^{-1}} < \varepsilon/2$, and thus we have $\|u(t_0)\|_{\chi^{-1}} \leq \|v(t_0)\|_{\chi^{-1}} + \|w(t_0)\|_{\chi^{-1}} < \varepsilon$. So, applying Theorem 2.5 for the data $u(t_0)$ we obtain

$$\|u(t)\|_{\chi^{-1}} \leq \|u(t_0)\|_{\chi^{-1}} < \varepsilon, \quad t > t_0,$$

which implies $\lim_{t \rightarrow \infty} \|u(t)\|_{\chi^{-1}} = 0$.

Here, we notice that in the final part of the proof we need the uniqueness of solutions, which is assured in our class of solutions. In fact, if u_1 , and $u_2 \in C([0, \infty); H^s)$ are two solutions to (NS_Ω) satisfying

$$u_1, u_2 \in AC([0, \infty); H^{s-1}(\mathbb{R}^3)) \cap L_{\text{loc}}^1(0, \infty; H^{s+1}(\mathbb{R}^3)),$$

then, $\tilde{u} := u_1 - u_2$ satisfies $\text{div} \tilde{u} = 0$ and

$$\partial_t \tilde{u} + \nu \Delta \tilde{u} + \Omega e_3 \times \tilde{u} + (\tilde{u}, \nabla) \tilde{u} + (u_1, \nabla) \tilde{u} + (\tilde{u}, \nabla) u_2 + \nabla(p_1 - p_2) = 0,$$

and thus we obtain

$$\frac{d}{dt} \|\tilde{u}(t)\|_{L^2}^2 + \frac{\nu}{2} \|\nabla \tilde{u}(t)\|_{L^2}^2 = |\langle (\tilde{u}, \nabla) u_2, \tilde{u} \rangle_{L^2}| \leq \|\nabla u_2(t)\|_{L^\infty}^2 \|\tilde{u}(t)\|_{L^2}^2.$$

Therefore, we have

$$\frac{d}{dt} \|\tilde{u}(t)\|_{L^2}^2 = C \|u_2(t)\|_{H^{s+1}} \|\tilde{u}(t)\|_{L^2}^2$$

and Gronwall's inequality implies $\tilde{u}(t) = 0$ for $t > 0$.

Chapter 3

χ^{-1} Theory

3.1 Main Theorem in χ^{-1} Theory

In this section, we state our main result and representation of the solution of linearized equation of (NS_Ω) .

Theorem 3.1. *Let $u_0 \in \chi^{-1}$ and $\|u_0\|_{\chi^{-1}} < (2\pi)^3\nu$. Then, there is a unique global in time solution $u \in C([0, \infty); \chi^{-1})$ of (NS_Ω) satisfying*

$$u \in L^2(0, \infty; \chi^0) \cap L^1(0, \infty; \chi^1), \quad \partial_t u \in L^1(0, \infty; \chi^{-1}),$$

and

$$\sup_{t>0} \left\{ \|u(t)\|_{\chi^{-1}} + (\nu - (2\pi)^{-3}\|u_0\|_{\chi^{-1}}) \int_0^t \|u(\tau)\|_{\chi^1} d\tau \right\} \leq \|u_0\|_{\chi^{-1}}.$$

Remark 3.2. In the Navier-Stokes equations, the case $\Omega = 0$, the corresponding result is proved in [12, Theorem 1.1]. We notice that there is also another approach by [14, Theorem 1.3]. The argument below is based on the latter.

For the proof of Theorem 3.1 we consider the integral equation

$$u(t) = \mathcal{S}(t)u_0 - \int_0^t \mathcal{S}(t-s)\mathbb{P}\nabla \cdot (u \otimes u)(s)ds, \quad (3.1.1)$$

where $\mathbb{P} = (\delta_{ij} + R_i R_j)_{i,j}$ denotes the Helmholtz projection, $R_j = \mathcal{F}^{-1} \frac{i\xi_j}{|\xi|} \mathcal{F}$ denotes the Riesz transforms, and $\nabla \cdot (u \otimes u) = (\sum_j \partial_j (u_i u_j))_{i=1,2,3}$. Here

$\mathcal{S}(t)$ represents the semigroup corresponding to the linear problem

$$\begin{cases} \partial_t v - \nu \Delta v + \Omega e_3 \times v + \nabla q = 0, \\ \operatorname{div} v = 0, \\ v|_{t=0} = v_0, \end{cases} \quad (3.1.2)$$

which is given explicitly by

$$\widehat{\mathcal{S}(t)v_0}(\xi) = \cos\left(\Omega \frac{\xi_3}{|\xi|} t\right) e^{-\nu|\xi|^2 t} I \widehat{v}_0(\xi) + \sin\left(\Omega \frac{\xi_3}{|\xi|} t\right) e^{-\nu|\xi|^2 t} R(\xi) \widehat{v}_0(\xi),$$

where I is the 3×3 identity matrix and

$$R(\xi) = \begin{pmatrix} 0 & \frac{\xi_3}{|\xi|} & -\frac{\xi_2}{|\xi|} \\ -\frac{\xi_3}{|\xi|} & 0 & \frac{\xi_1}{|\xi|} \\ \frac{\xi_2}{|\xi|} & -\frac{\xi_1}{|\xi|} & 0 \end{pmatrix}.$$

For its derivation, see e.g. [8]. The integral equation (3.1.1) formally derived as follows. We first apply \mathbb{P} to the equation, then we have

$$\partial_t u - \nu \Delta u + \Omega \mathbb{P} e_3 \times u + \mathbb{P} \nabla \cdot (u \otimes u) = 0, \quad (3.1.3)$$

where $(u, \nabla u) = \nabla \cdot (u \otimes u)$ holds since $\operatorname{div} u = 0$. Here, we notice that

$$\Omega \mathbb{P} e_3 \times u = \Omega e_3 \times u + \nabla q \quad (3.1.4)$$

holds, where q denotes the pressure to the linear problem (3.1.2). Indeed, taking div to the first equation of (3.1.2), we have

$$\operatorname{div} \partial_t u - \nu \operatorname{div} \Delta u + \Omega \operatorname{div} (e_3 \times u) + \Delta q = 0.$$

Since $\operatorname{div} u = 0$, it follows that

$$\begin{aligned} \Delta q &= -\Omega \operatorname{div} (e_3 \times u) \\ &= \Omega (\partial_1 u_2 - \partial_2 u_1). \end{aligned}$$

Thus we have

$$\widehat{\nabla} q = i\xi \left(-\Omega \left(\frac{i\xi_1}{|\xi|^2} \widehat{u}_2 - \frac{i\xi_2}{|\xi|^2} \widehat{u}_1 \right) \right).$$

Since $\mathbb{P} = (\delta_{ij} + R_i R_j)_{i,j}$, we find that

$$\begin{aligned} \mathbb{P}e_3 \times u &= \mathbb{P} \begin{pmatrix} -u_2 \\ u_1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} -u_2 \\ u_1 \\ 0 \end{pmatrix} + \begin{pmatrix} -R_1^2 u_2 + R_1 R_2 u_1 \\ -R_2 R_1 u_2 + R_2^2 u_1 \\ -R_3 R_1 u_2 + R_3 R_2 u_1 \end{pmatrix} \\ &= e_3 \times u + \frac{1}{\Omega} \nabla q, \end{aligned}$$

by definition of R_j . Thus, we obtain the equation

$$\begin{cases} \partial_t u - \nu \Delta u + \Omega e_3 \times u + \nabla q = -\mathbb{P}(u, \nabla)u, \\ \operatorname{div} u = 0, \\ u|_{t=0} = u_0, \end{cases} \quad (3.1.5)$$

Therefore, by Duhamel's principle, we obtain (3.1.1).

3.2 Existence of Solutions for Any Time Interval

In this section, we state there exists a local solution of (NS_Ω) if $\|u_0\|_{\chi^{-1}} \leq 4\pi^3 \nu$. First we prove the following lemma about $\mathcal{S}(t)$.

Lemma 3.3. *For $u \in \mathcal{S}'$ and $\widehat{u} \in L_{\text{loc}}^1$, we have*

$$|\widehat{\mathbb{P}u}(\xi)| \leq |\widehat{u}(\xi)|,$$

and

$$|\widehat{\mathcal{S}(t)u}(\xi)| \leq e^{-\nu|\xi|^2 t} |\widehat{u}(\xi)|.$$

proof. By definition of \mathbb{P} , we have

$$\begin{aligned}
|\widehat{\mathbb{P}u}(\xi)| &= \left| \mathcal{F} \begin{pmatrix} u_1 + R_1 \sum_{j=1}^3 R_j u_j \\ u_2 + R_2 \sum_{j=1}^3 R_j u_j \\ u_3 + R_3 \sum_{j=1}^3 R_j u_j \end{pmatrix} \right| \\
&= \left| \begin{pmatrix} \widehat{u}_1 + \frac{i\xi_1}{|\xi|} \sum_{j=1}^3 \frac{i\xi_j}{|\xi|} \widehat{u}_j \\ \widehat{u}_2 + \frac{i\xi_2}{|\xi|} \sum_{j=1}^3 \frac{i\xi_j}{|\xi|} \widehat{u}_j \\ \widehat{u}_3 + \frac{i\xi_3}{|\xi|} \sum_{j=1}^3 \frac{i\xi_j}{|\xi|} \widehat{u}_j \end{pmatrix} \right| \\
&= \left| \begin{pmatrix} \widehat{u}_1 - \frac{\xi_1}{|\xi|^2} (\xi \cdot \widehat{u}) \\ \widehat{u}_2 - \frac{\xi_2}{|\xi|^2} (\xi \cdot \widehat{u}) \\ \widehat{u}_3 - \frac{\xi_3}{|\xi|^2} (\xi \cdot \widehat{u}) \end{pmatrix} \right| \\
&= \sqrt{|\widehat{u}|^2 - \frac{2}{|\xi|^2} (\xi \cdot \widehat{u})^2 + \frac{\xi_1^2 + \xi_2^2 + \xi_3^2}{|\xi|^4} (\xi \cdot \widehat{u})^2} \\
&= \sqrt{|\widehat{u}|^2 - \frac{1}{|\xi|^2} (\xi \cdot \widehat{u})^2} \leq |\widehat{u}(\xi)|.
\end{aligned}$$

By definition of $R(\xi)$, we have

$$R(\xi)u = \frac{\xi}{|\xi|} \times u.$$

It follows that

$$\begin{aligned}
e^{2\nu|\xi|^2 t} |\widehat{\mathcal{S}(t)u}(\xi)|^2 &= \left| \cos \left(\Omega \frac{\xi_3}{|\xi|} t \right) \widehat{u}(\xi) + \sin \left(\Omega \frac{\xi_3}{|\xi|} t \right) \frac{\xi}{|\xi|} \times \widehat{u}(\xi) \right|^2 \\
&= \cos^2 \left(\Omega \frac{\xi_3}{|\xi|} t \right) |\widehat{u}(\xi)|^2 + \sin^2 \left(\Omega \frac{\xi_3}{|\xi|} t \right) \left| \frac{\xi}{|\xi|} \times \widehat{u}(\xi) \right|^2 \\
&\quad + 2 \cos \left(\Omega \frac{\xi_3}{|\xi|} t \right) \sin \left(\Omega \frac{\xi_3}{|\xi|} t \right) \widehat{u}(\xi) \cdot \left(\frac{\xi}{|\xi|} \times \widehat{u}(\xi) \right) \\
&= \cos^2 \left(\Omega \frac{\xi_3}{|\xi|} t \right) |\widehat{u}(\xi)|^2 + \sin^2 \left(\Omega \frac{\xi_3}{|\xi|} t \right) \left\{ |\widehat{u}(\xi)|^2 - \left(\frac{\xi}{|\xi|} \cdot \widehat{u}(\xi) \right)^2 \right\} \\
&= |\widehat{u}(\xi)|^2 - \sin^2 \left(\Omega \frac{\xi_3}{|\xi|} t \right) \left(\frac{\xi}{|\xi|} \cdot \widehat{u}(|\xi|) \right)^2 \\
&\leq |\widehat{u}(\xi)|^2.
\end{aligned}$$

□

Proposition 3.4. For any $T > 0$, we define $\mathcal{B} : L^2([0, T]; \chi^0) \times L^2([0, T]; \chi^0) \rightarrow L^2([0, T]; \chi^0)$ as

$$\mathcal{B}(u, v) = \int_0^t \mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes v) ds, \quad u, v \in L^2([0, T]; \chi^0).$$

Then, \mathcal{B} is the continuous bilinear map, and

$$\|\mathcal{B}\| := \sup_{\|u\| \leq 1, \|v\| \leq 1} \|\mathcal{B}(u, v)\|_{L^2_T \chi^0} \leq \frac{1}{\sqrt{2\nu}(2\pi)^3}.$$

proof. For $T > 0$ and $u, v \in L^2([0, T]; \chi^0)$, we have from Lemma 3.3

$$\begin{aligned} |\widehat{\mathcal{B}(u, v)}(t, \xi)| &\leq \int_0^t |\mathcal{F}[\mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes v)](s, \xi)| ds \\ &\leq \int_0^t e^{-\nu(t-s)|\xi|^2} |\mathcal{F}[\mathbb{P} \nabla \cdot (u \otimes v)](s, \xi)| ds \\ &\leq \int_0^t e^{-\nu(t-s)|\xi|^2} |\mathcal{F}[\nabla \cdot (u \otimes v)](s, \xi)| ds \\ &\leq \frac{1}{(2\pi)^3} \int_0^t e^{-\nu(t-s)|\xi|^2} |\xi| |\widehat{u}| * |\widehat{v}|(s, \xi) ds. \end{aligned}$$

Using Minkowski's integral inequality and Young's inequality, we have

$$\begin{aligned}
\|\mathcal{B}(u, v)\|_{L^2([0, T]; \chi^0)} &= \left(\int_0^T \|\mathcal{B}(u, v)\|_{\chi^0}^2 dt \right)^{\frac{1}{2}} = \left(\int_0^T \left(\int_{\mathbb{R}^3} |\widehat{\mathcal{B}(u, v)}(t, \xi)| d\xi \right)^2 dt \right)^{\frac{1}{2}} \\
&\leq \frac{1}{(2\pi)^3} \left(\int_0^T \left(\int_{\mathbb{R}^3} \int_0^t e^{-\nu(t-s)|\xi|^2} |\xi| |\widehat{u}| * |\widehat{v}| ds d\xi \right)^2 dt \right)^{\frac{1}{2}} \\
&= \frac{1}{(2\pi)^3} \left(\int_0^T \left(\int_{\mathbb{R}^3} \int_0^T \chi_{[0, t]}(s) e^{-\nu(t-s)|\xi|^2} |\xi| |\widehat{u}| * |\widehat{v}| ds d\xi \right)^2 dt \right)^{\frac{1}{2}} \\
&\leq \frac{1}{(2\pi)^3} \int_{\mathbb{R}^3} \int_0^T \left(\int_s^T e^{-2\nu(t-s)|\xi|^2} |\xi|^2 (|\widehat{u}| * |\widehat{v}|(s, \xi))^2 dt \right)^{\frac{1}{2}} ds d\xi \\
&= \frac{1}{(2\pi)^3} \int_{\mathbb{R}^3} \int_0^T |\xi| |\widehat{u}| * |\widehat{v}|(s, \xi) \left(\int_s^T e^{-2\nu(t-s)|\xi|^2} dt \right)^{\frac{1}{2}} ds d\xi \\
&\leq \frac{1}{\sqrt{2\nu}(2\pi)^3} \int_{\mathbb{R}^3} \int_0^T |\widehat{u}| * |\widehat{v}|(s, \xi) ds d\xi \\
&\leq \frac{1}{\sqrt{2\nu}(2\pi)^3} \int_0^T \|\widehat{u}(s, \cdot)\|_{L^1} \|\widehat{v}(s, \cdot)\|_{L^1} ds \\
&\leq \frac{1}{\sqrt{2\nu}(2\pi)^3} \|u\|_{L^2([0, T]; \chi^0)} \|v\|_{L^2([0, T]; \chi^0)},
\end{aligned}$$

where $\chi_{[0, t]}$ is characteristic function on $[0, t]$. Thus we conclude

$$\|\mathcal{B}\| \leq \frac{1}{\sqrt{2\nu}(2\pi)^3}.$$

□

Theorem 3.5. *Let u_0 be in χ^{-1} and $\|u_0\|_{\chi^{-1}} \leq 4\pi^3\nu$. For any $T > 0$, there is a unique solution $u \in L^2([0, T]; \chi^0)$ of (NS_Ω) such that $\|u\|_{L^2([0, T]; \chi^0)} \leq 2\pi^3\sqrt{2\nu}$.*

Now we use the following lemma to prove this.

Lemma 3.6 ([2]). *Let E be a Banach space, \mathcal{B} a continuous bilinear map from $E \times E \rightarrow E$, and a positive real number α such that $\alpha < \frac{1}{4\|\mathcal{B}\|}$. For any*

a in the ball $B(0, \alpha) = \{x \in E; \|x\|_E \leq \alpha\}$, then there exists a unique x in $B(0, 2\alpha)$ such that $x = a + B(x, x)$.

Using Lemma 3.6, we can prove Theorem.

proof. Using $\|\mathcal{B}\| \leq \frac{1}{\sqrt{2\nu}(2\pi)^3}$, we can get for any $T > 0$,

$$\begin{aligned} \|\mathcal{S}(t)u_0\|_{L^2([0, T]; \chi^0)} &\leq \left(\int_0^T \left(\int_{\mathbb{R}^3} e^{-\nu|\xi|^2 t} |\widehat{u}_0(\xi)| d\xi \right)^2 dt \right)^{\frac{1}{2}} \\ &\leq \int_{\mathbb{R}^3} \left(\int_0^T e^{-2\nu|\xi|^2 t} |\widehat{u}_0(\xi)|^2 dt \right)^{\frac{1}{2}} d\xi \\ &\leq \int_{\mathbb{R}^3} \frac{|\widehat{u}_0(\xi)|}{(2\nu)^{\frac{1}{2}} |\xi|} d\xi = \frac{1}{(2\nu)^{\frac{1}{2}}} \|u_0\|_{\chi^{-1}}. \end{aligned}$$

Since $\|u_0\|_{\chi^{-1}} \leq 4\pi^3\nu$, we have $\frac{1}{(2\nu)^{\frac{1}{2}}} \|u_0\|_{\chi^{-1}} \leq \frac{\sqrt{2\nu}(2\pi)^3}{4} \leq \frac{1}{4\|\mathcal{B}\|}$.

So using Lemma 3.6 for $\alpha = \sqrt{2\nu}\pi^3$, $E = L^2([0, T]; \chi^0)$ and $a = \mathcal{S}(t)u_0$, we can conclude there exists a unique u in $B(0, 2\alpha)$ such that $u = \mathcal{S}(t)u_0 + \mathcal{B}(u, u)$. Moreover, we have $\|u\|_{L^2([0, T]; \chi^0)} \leq 2 \cdot \sqrt{2\nu}\pi^3 = 2\pi^3\sqrt{2\nu}$. \square

3.3 Existence of Local Solutions for Any Initial Data

In this section we prove existence of local solutions for any initial data in χ^{-1} .

Theorem 3.7. *For any $u_0 \in \chi^{-1}$, there exists a positive number $\rho = \rho_{u_0} > 0$ and $T = T(\nu, \|u_0\|_{\chi^{-1}}, \rho) > 0$ such that (NS_Ω) has a unique solution $u \in C([0, T]; \chi^{-1})$ satisfying*

$$u \in L^2(0, T; \chi^0) \cap L^1(0, T; \chi^1), \quad \partial_t u \in L^1(0, T; \chi^{-1}).$$

Remark 3.8. T is determined by

$$T = \frac{\pi^6 \nu}{2\rho_{u_0}^2 \|u_0\|_{\chi^{-1}}^2}.$$

proof. We fix some positive number $\rho_{u_0} > 0$ such that

$$\int_{|\xi| \geq \rho_{u_0}} \frac{|\widehat{u}_0(\xi)|}{|\xi|} d\xi \leq \pi^3 \nu.$$

Defining $u_0^b = \mathcal{F}^{-1}(\chi_{B(0, \rho_{u_0})}(\xi) \widehat{u}_0(\xi))$, we get

$$\begin{aligned} \|\mathcal{S}(t)u_0^b\|_{L^2([0, T]; \chi^0)} &= \left(\int_0^T \left(\int_{\mathbb{R}^3} |\mathcal{F}[\mathcal{S}(t)u_0^b](\xi)| d\xi \right)^2 dt \right)^{\frac{1}{2}} \\ &\leq \left(\int_0^T \left(\int_{|\xi| \leq \rho_{u_0}} |\widehat{u}_0^b(\xi)| d\xi \right)^2 dt \right)^{\frac{1}{2}} \\ &\leq \left(\int_0^T \left(\int_{|\xi| \leq \rho_{u_0}} |\xi| \cdot \frac{1}{|\xi|} |\widehat{u}_0(\xi)| d\xi \right)^2 dt \right)^{\frac{1}{2}} \\ &\leq \rho_{u_0} \|u_0\|_{\chi^{-1}} T^{\frac{1}{2}}. \end{aligned}$$

So using Minkowski inequality, we deduce that

$$\begin{aligned} \|\mathcal{S}(t)u_0\|_{L^2([0, T]; \chi^0)} &\leq \|\mathcal{S}(t)(u_0 - u_0^b)\|_{L^2([0, T]; \chi^0)} + \|\mathcal{S}(t)u_0^b\|_{L^2([0, T]; \chi^0)} \\ &\leq \left(\int_0^T \left(\int_{|\xi| \geq \rho_{u_0}} e^{-\nu|\xi|^2 t} |\widehat{u}_0(\xi)| d\xi \right)^2 dt \right)^{\frac{1}{2}} + \rho_{u_0} \|u_0\|_{\chi^{-1}} T^{\frac{1}{2}} \\ &\leq \int_{|\xi| \geq \rho_{u_0}} \left(\int_0^T e^{-2\nu|\xi|^2 t} |\widehat{u}_0(\xi)|^2 dt \right)^{\frac{1}{2}} d\xi + \rho_{u_0} \|u_0\|_{\chi^{-1}} T^{\frac{1}{2}} \\ &\leq \frac{1}{\sqrt{2\nu}} \int_{|\xi| \geq \rho_{u_0}} \frac{|\widehat{u}_0(\xi)|}{|\xi|} d\xi + \rho_{u_0} \|u_0\|_{\chi^{-1}} T^{\frac{1}{2}} \\ &\leq \frac{1}{\sqrt{2\nu}} \cdot \pi^3 \nu + \rho_{u_0} \|u_0\|_{\chi^{-1}} T^{\frac{1}{2}}. \end{aligned}$$

So if

$$T = \frac{\pi^6 \nu}{2\rho_{u_0}^2 \|u_0\|_{\chi^{-1}}^2}, \quad (3.3.1)$$

we get

$$\|\mathcal{S}(t)u_0\|_{L^2([0, T]; \chi^0)} \leq \sqrt{2\nu} \pi^3.$$

By Lemma 3.6, this implies that (NS_Ω) has a unique solution u in $L^2([0, T]; \chi^0)$.

Now we show $u \in L^1([0, T]; \chi^1)$.

$$\begin{aligned}
\|S(t)u_0\|_{L_T^1 \chi^1} &= \int_0^T \|S(t)u_0\|_{\chi^1} dt \\
&= \int_0^T \int_{\mathbb{R}^3} |\xi| |\widehat{S(t)u_0}(\xi)| d\xi dt \\
&\leq \int_{\mathbb{R}^3} |\xi| |\widehat{u_0}(\xi)| \int_0^T e^{-\nu|\xi|^2 t} dt d\xi \\
&\leq \int_{\mathbb{R}^3} \frac{|\xi|}{\nu|\xi|^2} |\widehat{u_0}(\xi)| d\xi \\
&= \frac{1}{\nu} \|u_0\|_{\chi^{-1}}.
\end{aligned}$$

Similarly, we see that by Lemma 3.3

$$\begin{aligned}
&\left\| \int_0^t \mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)(s) ds \right\|_{L_T^1 \chi^1} \\
&\leq \int_0^T \int_{\mathbb{R}^3} |\xi| \int_0^t |\mathcal{F}[\mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)](s, \xi)| ds d\xi dt \\
&\leq \int_0^T \int_{\mathbb{R}^3} |\xi| \int_0^t e^{-\nu|\xi|^2(t-s)} |\mathcal{F}[\mathbb{P} \nabla \cdot (u \otimes u)](s, \xi)| ds d\xi dt \\
&\leq \int_0^T \int_{\mathbb{R}^3} \int_0^t e^{-\nu|\xi|^2(t-s)} \frac{|\xi|^2}{(2\pi)^3} |\widehat{u}| * |\widehat{u}|(s, \xi) ds d\xi dt \\
&\leq \int_0^T \int_{\mathbb{R}^3} \frac{1}{\nu(2\pi)^3} |\widehat{u}| * |\widehat{u}|(s, \xi) d\xi ds \\
&\leq \frac{1}{\nu(2\pi)^3} \int_0^T \|u(s)\|_{\chi^0}^2 ds.
\end{aligned}$$

Therefore we obtain that $u \in L^1([0, T]; \chi^1)$.

We see $u \in L_T^\infty \chi^{-1}$. Indeed, we have

$$\begin{aligned}
\|\mathcal{S}(t)u_0\|_{L_T^\infty \chi^{-1}} &= \sup_{0 \leq t \leq T} \|\mathcal{S}(t)u_0\|_{\chi^{-1}} \\
&= \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} |\widehat{\mathcal{S}(t)u_0}(\xi)| d\xi \\
&\leq \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} e^{-\nu|\xi|^2 t} |\widehat{u_0}(\xi)| d\xi \\
&\leq \int_{\mathbb{R}^3} |\xi|^{-1} |\widehat{u_0}(\xi)| d\xi = \|u_0\|_{\chi^{-1}}.
\end{aligned}$$

Moreover using Lemma 3.3 and Hausdorff-Young inequality, we obtain

$$\begin{aligned}
&\left\| \int_0^t \mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)(s) ds \right\|_{L_T^\infty \chi^{-1}} \\
&\sup_{0 \leq t \leq T} \left\| \int_0^t \mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)(s) ds \right\|_{\chi^{-1}} \\
&= \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} \left| \mathcal{F} \left[\int_0^t \mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)(s) ds \right] (\xi) \right| d\xi \\
&= \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} \left| \int_0^t \mathcal{F} [\mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)(s)] (s, \xi) ds \right| d\xi \\
&\leq \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} \int_0^t |\mathcal{F} [\mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u)(s)] (s, \xi)| ds d\xi \\
&\leq \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} \int_0^t e^{-\nu|\xi|^2(t-s)} |\mathcal{F} [\mathbb{P} \nabla \cdot (u \otimes u)(s)] (s, \xi)| ds d\xi \\
&\leq \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} \int_0^t e^{-\nu|\xi|^2(t-s)} |\mathcal{F} [\nabla \cdot (u \otimes u)(s)] (s, \xi)| ds d\xi \\
&\leq \sup_{0 \leq t \leq T} \int_{\mathbb{R}^3} |\xi|^{-1} \int_0^t e^{-\nu|\xi|^2(t-s)} \frac{1}{(2\pi)^3} |\xi| |\widehat{u}| * |\widehat{u}|(s, \xi) ds d\xi \\
&\leq \frac{1}{(2\pi)^3} \sup_{0 \leq t \leq T} \int_0^t \int_{\mathbb{R}^3} |\widehat{u}| * |\widehat{u}|(s, \xi)(s, \xi) d\xi ds \\
&\leq \frac{1}{(2\pi)^3} \sup_{0 \leq t \leq T} \int_0^t \|u(s)\|_{\chi^0}^2 ds \\
&\leq \frac{1}{(2\pi)^3} \int_0^T \|u(s)\|_{\chi^0}^2 ds.
\end{aligned}$$

It follows that $u \in L_T^\infty \chi^{-1}$.

Next we prove $\partial_t u \in L^1([0, T]; \chi^{-1})$, which implies $u \in C([0, T]; \chi^{-1})$. We have

$$\partial_t u(t) = \nu \Delta u(t) - \Omega \mathbb{P}e_3 \times u(t) - \mathbb{P}\nabla \cdot (u \otimes u)$$

in the distribution sense.

Then we see that

$$\int_0^T \|\Delta u(t)\|_{\chi^{-1}} dt \leq \int_0^T \int_{\mathbb{R}^3} |\xi| |\widehat{u}(t, \xi)| d\xi dt = \|u\|_{L_T^1 \chi^1}$$

and

$$\begin{aligned} \int_0^T \|\mathbb{P}\nabla \cdot (u \otimes u)\|_{\chi^{-1}} dt &\leq \int_0^T \int_{\mathbb{R}^3} \frac{1}{|\xi|} |\mathcal{F}[\nabla \cdot (u \otimes u)](t, \xi)| d\xi dt \\ &\leq \int_0^T \int_{\mathbb{R}^3} |\widehat{u}| * |\widehat{u}| d\xi dt \\ &\leq \frac{1}{(2\pi)^3} \|u\|_{L_T^2 \chi^0}. \end{aligned}$$

Since $u \in L_T^\infty \chi^{-1}$, we see

$$\int_0^T \|\Omega \mathbb{P}e_3 \times u(t)\|_{\chi^{-1}} dt \leq \Omega T \|u\|_{L_T^\infty \chi^{-1}}.$$

Thus we have $\partial_t u \in L^1([0, T]; \chi^{-1})$. Finally, we prove uniqueness of the solution to (NS_Ω) in $L_T^\infty \chi^{-1} \cap L_T^1 \chi^1$. For $u, v \in L_T^\infty \chi^{-1} \cap L_T^1 \chi^1$, we set $w := u - v$. Then, we observe

$$\begin{aligned} w(t) &= \left\{ \mathcal{S}(t)u_0 - \int_0^t \mathcal{S}(t-s) \mathbb{P}\nabla \cdot (u \otimes u)(s) ds \right\} \\ &\quad - \left\{ \mathcal{S}(t)u_0 - \int_0^t \mathcal{S}(t-s) \mathbb{P}\nabla \cdot (v \otimes v)(s) ds \right\} \\ &= - \int_0^t \mathcal{S}(t-s) \mathbb{P}\nabla \cdot (u \otimes u - v \otimes v)(s) ds. \end{aligned}$$

So by Lemma 3.3, we see

$$\begin{aligned}
|\widehat{w}(t, \xi)| &= \left| \mathcal{F} \left[\int_0^t \mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u - v \otimes v)(s) ds \right] (\xi) \right| \\
&\leq \int_0^t |\mathcal{F} [\mathcal{S}(t-s) \mathbb{P} \nabla \cdot (u \otimes u - v \otimes v)](s, \xi)| ds \\
&\leq \int_0^t e^{-\nu|\xi|^2(t-s)} |\mathcal{F} [\mathbb{P} \nabla \cdot (u \otimes u - v \otimes v)](s, \xi)| ds \\
&\leq \int_0^t e^{-\nu|\xi|^2(t-s)} |\mathcal{F} [\nabla \cdot (u \otimes (u-v) + (u-v) \otimes v)](s, \xi)| ds \\
&\leq \frac{1}{(2\pi)^3} \int_0^t e^{-\nu|\xi|^2(t-s)} |\xi| (|\widehat{u}| * |\widehat{w}|(s, \xi) + |\widehat{w}| * |\widehat{v}|(s, \xi)) ds.
\end{aligned}$$

Then we have

$$\begin{aligned}
\|w(t)\|_{\chi^{-1}} &\leq \frac{1}{(2\pi)^3} \int_{\mathbb{R}^3} \int_0^t \{(|\widehat{u}| * |\widehat{w}|)(s, \xi) + (|\widehat{w}| * |\widehat{v}|)(s, \xi)\} ds d\xi \\
&\leq \frac{1}{(2\pi)^3} \int_0^t (\|u(s)\|_{\chi^0} + \|v(s)\|_{\chi^0}) \|w(s)\|_{\chi^0} ds.
\end{aligned}$$

Using Lemma 2.1, for $\varepsilon > 0$, there exists a positive number C_ε such that

$$\begin{aligned}
\|u(s)\|_{\chi^0} \|w(s)\|_{\chi^0} &\leq \|u(s)\|_{\chi^1}^{\frac{1}{2}} \|u(s)\|_{\chi^{-1}}^{\frac{1}{2}} \cdot \|w(s)\|_{\chi^1}^{\frac{1}{2}} \|w(s)\|_{\chi^{-1}}^{\frac{1}{2}} \\
&\leq C_\varepsilon \|u(s)\|_{\chi^1} \|w(s)\|_{\chi^{-1}} + \varepsilon \|u(s)\|_{\chi^{-1}} \|w(s)\|_{\chi^1}.
\end{aligned}$$

Thus we have

$$\|w\|_{L_T^\infty \chi^{-1}} \leq \varepsilon \|u\|_{L_T^\infty \chi^{-1}} \|w\|_{L_T^1 \chi^1} + C_\varepsilon \|u\|_{L_T^1 \chi^1} \|w\|_{L_T^\infty \chi^{-1}}.$$

Similarly we see

$$\nu \|w\|_{L_T^1 \chi^1} \leq \varepsilon \|u\|_{L_T^\infty \chi^{-1}} \|w\|_{L_T^1 \chi^1} + C_\varepsilon \|u\|_{L_T^1 \chi^1} \|w\|_{L_T^\infty \chi^{-1}}.$$

Here we take sufficiently small $\varepsilon > 0$ such that

$$\varepsilon \|u\|_{L_T^\infty \chi^{-1}} < \frac{\nu}{4}.$$

Furthermore, if we take $\delta > 0$ such that

$$C_\varepsilon \|u\|_{L_\delta^1 \chi^1} < \frac{1}{4},$$

we have

$$\begin{aligned} \|w\|_{L^\infty_\delta \chi^{-1}} + \nu \|w\|_{L^1_\delta \chi^1} &\leq 2\varepsilon \|u\|_{L^\infty_\delta \chi^{-1}} \|w\|_{L^1_\delta \chi^1} + 2C_\varepsilon \|u\|_{L^1_\delta \chi^1} \|w\|_{L^\infty_\delta \chi^{-1}} \\ &\leq \frac{1}{2} (\|w\|_{L^\infty_\delta \chi^{-1}} + \nu \|w\|_{L^1_\delta \chi^1}). \end{aligned}$$

Thus we deduce $\|w\|_{L^\infty_\delta \chi^{-1}} + \nu \|w\|_{L^1_\delta \chi^1} = 0$. Therefore, we have

$$w(t) = 0, \quad t \in [0, \delta].$$

Repeating this argument, we see uniqueness of the solution. \square

3.4 Proof of Theorem 3.1

In this section, we prove Theorem 3.1.

proof. Let T^* be the maximal existence time of a solution of (NS_Ω) , derived by applying Theorem 3.7 repeatedly. Suppose $T^* < \infty$. By (3.3.1), we must have

$$\lim_{t \rightarrow T^*} \|u(t)\|_{\chi^{-1}} = \infty,$$

or

$$\lim_{t \rightarrow T^*} \rho(t) = \infty, \quad (3.4.1)$$

where $\rho(t)$ is determined by

$$\rho(t) = \inf \left\{ \rho > 0; \int_{|\xi| \geq \rho} \frac{|\widehat{u}(t, \xi)|}{|\xi|} d\xi \leq \pi^3 \nu \right\}.$$

We easily observe that $\sup_{0 < t < T^*} \|u(t)\|_{\chi^{-1}} \leq \|u_0\|_{\chi^{-1}}$ by Theorem 2.3. So, it suffices to show that (3.4.1) would never happen. For $0 < t < T^*$, we find that

$$\begin{aligned} |\widehat{u}(t, \xi)| &\leq |\widehat{\mathcal{S}(t)u_0}(\xi)| + \int_0^t |\mathcal{F}[\mathcal{S}(t-s)\mathbb{P}\nabla \cdot (u \otimes u)](s, \xi)| ds \\ &\leq e^{-\nu|\xi|^2 t} |\widehat{u}_0(\xi)| + \int_0^t e^{-\nu(t-s)|\xi|^2} |\mathcal{F}[\nabla \cdot (u \otimes u)](s, \xi)| ds \\ &\leq |\widehat{u}_0(\xi)| + \int_0^t e^{-\nu(t-s)|\xi|^2} |\mathcal{F}[\nabla \cdot (u \otimes u)](s, \xi)| ds \\ &\leq |\widehat{u}_0(\xi)| + \int_0^t e^{-\nu(t-s)|\xi|^2} \frac{|\xi|}{(2\pi)^3} |\widehat{u}| * |\widehat{u}|(s, \xi) ds. \end{aligned}$$

Hence we see that

$$\begin{aligned}
\int_{\mathbb{R}^3} \sup_{0 \leq t \leq T^*} |\widehat{u}(t, \xi)| \frac{1}{|\xi|} d\xi &\leq \|u_0\|_{\chi^{-1}} + \int_{\mathbb{R}^3} \int_0^{T^*} \frac{1}{(2\pi)^3} |\widehat{u}| * |\widehat{u}|(s, \xi) ds d\xi \\
&\leq \|u_0\|_{\chi^{-1}} + \frac{1}{(2\pi)^3} \int_0^{T^*} \|u(s)\|_{\chi^0}^2 ds \\
&\leq \|u_0\|_{\chi^{-1}} + \frac{1}{(2\pi)^3} \|u\|_{L^2([0, T^*]; \chi^0)}^2.
\end{aligned}$$

Applying Theorem 2.3, we obtain that

$$\begin{aligned}
\|u\|_{L^2([0, T^*]; \chi^0)}^2 &= \int_0^{T^*} \|u(t)\|_{\chi^0}^2 dt \\
&\leq \int_0^{T^*} \|u(t)\|_{\chi^{-1}} \|u(t)\|_{\chi^1} dt \\
&\leq \|u_0\|_{\chi^{-1}} \cdot \frac{\|u_0\|_{\chi^{-1}}}{\nu - \frac{1}{(2\pi)^3} \|u_0\|_{\chi^{-1}}}.
\end{aligned}$$

Thus we have there exists some $M > 0$, such that

$$\int_{\mathbb{R}^3} \sup_{0 \leq t \leq T^*} |\widehat{u}(t, \xi)| \frac{1}{|\xi|} d\xi < M.$$

This implies that we are able to take $\rho > 0$ such that

$$\int_{|\xi| > \rho} \sup_{0 \leq t \leq T^*} |\widehat{u}(t, \xi)| \frac{1}{|\xi|} d\xi < \pi^3 \nu,$$

we get for any $0 < t < T^*$,

$$\int_{|\xi| > \rho} |\widehat{u}(t, \xi)| \frac{1}{|\xi|} d\xi < \int_{|\xi| > \rho} \sup_{0 \leq t \leq T^*} \frac{|\widehat{u}(t, \xi)|}{|\xi|} d\xi < \pi^3 \nu.$$

This contradicts to (3.4.1). □

Bibliography

- [1] A. Babin, A. Mahalov, B. Nicolaenko, Regularity and integrability of 3D Euler and Navier-Stokes equations for rotating fluids, *Asymptot. Anal.* **15** (1997), 103 – 150.
- [2] H. Bahouri, J.-Y. Chemin, R. Danchin, *Fourier Analysis and Nonlinear Partial Differential Equations*, Grundlehren der Mathematischen Wissenschaften, Vol. 343. New York: Springer-Verlag (2011).
- [3] J. Benameur, Long time decay to the Lei-Lin solution of 3D Navier-Stokes equations, *J. Math. Anal. Appl.* **422** (2015), 424 – 434.
- [4] J.-Y. Chemin, B. Desjardins, I. Gallagher, E. Grenier, “Mathematical geophysics. An introduction to rotating fluids and the Navier-Stokes equations.” *Oxford Lecture Series in Mathematics and its Applications* **32**, Oxford University Press (2006).
- [5] Y. Giga, K. Inui, A. Mahalov, J. Saal, Uniform global solvability of the rotating Navier-Stokes equations for nondecaying initial data, *Indiana Univ. Math. J.* **57** (2008), 2775 – 2791.
- [6] H. Ito, J. Kato, A remark on a priori estimate for the Navier-Stokes equations with the Coriolis force, [arXiv:1512.01814](https://arxiv.org/abs/1512.01814).
- [7] H. Ito, J. Kato, Blow-up criterion for the Navier-Stokes equations with the Coriolis force, in preparation.
- [8] M. Hieber, Y. Shibata, The Fujita-Kato approach to the Navier-Stokes equations in the rotational framework, *Math. Z.* **265** (2010), 481 – 491.
- [9] T. Iwabuchi, R. Takada, Global solutions for the Navier-Stokes equations in the rotational framework *Math. Ann.* **357** (2013), 727 – 741.

- [10] T. Iwabuchi, R. Takada, Global well-posedness and ill-posedness for the Navier-Stokes equations with the Coriolis force in function spaces of Besov type, *J. Funct. Anal.* **267** (2014), 1321 – 1337.
- [11] P. Konieczny, T. Yoneda, On dispersive effect of the Coriolis force for the stationary Navier-Stokes equations, *J. Differential Equations* **250** (2011), 3859 – 3873.
- [12] Z. Lei, F. Lin, Global mild solutions of Navier-Stokes equations, *Comm. Pure Anal. Math.* **64** (2011), 1297 – 1304.
- [13] Y. Koh, S. Lee, R. Takada, Strichartz estimates for the Euler equations in the rotational framework, *J. Differential Equations* **256** (2014), 707 – 744.
- [14] Z. Zhang, Z. Yin, Global well-posedness for the generalized Navier-Stokes system, arXiv:1306.3735.